

Formalisation of Nominal Equational Reasoning

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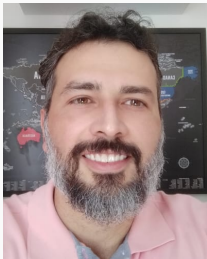


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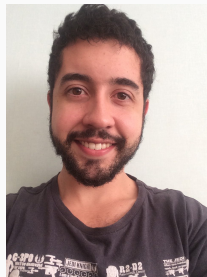
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1. Motivation

- Synthesis on Unification modulo

2. Bindings and Nominal Syntax

3. Nominal C-unification

4. Issues Adapting First-Order to Nominal AC-Unification

- An Algorithm for Nominal AC-Matching

5. Synthesis on Nominal Equational Modulo

6. Work in Progress and Future Work

Motivation

Equational Problems

- **Equality check:** $s = t?$
- **Matching:** There exists σ such that $s\sigma = t?$
- **Unification:** There exists σ such that $s\sigma = t\sigma?$

s and t are *terms* in some *signature* and σ is a *substitution*.

Equational Problems - Syntactic Unification

- Goal: *to identify* two expressions.
- Method: replace variables by other expressions.

Example: for x and y variables, a and b constants, and f a function symbol,

- *Identify* $f(x, a)$ and $f(b, y)$

Equational Problems - Syntactic Unification

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- Method: replace variables by other expressions.

Example: for x and y variables, a and b constants, and f a function symbol,

- *Identify* $f(x, a)$ and $f(b, y)$
- solution $\{x/b, y/a\}$.

Equational Problems - Syntactic unification

- \mathcal{F} set of function symbols.
- \mathcal{V} set of variables.
- x, y, z variables.
- a, b, c constant symbols.
- f, g, h function symbols.
- $\mathcal{T}(\mathcal{F}, \mathcal{V})$ set of terms over \mathcal{F} and \mathcal{V} .
- s, t, u terms.
- $\sigma, \gamma, \delta : \mathcal{V} \rightarrow \mathcal{T}(\mathcal{F}, \mathcal{V})$ set of substitutions.

Substitutions have finite domain: $\{v \mid v\sigma \neq v\}$ is finite.

Example:

- Solution $\sigma = \{x/b\}$ for $f(x, y) = f(b, y)$ is *more general* than solution $\gamma = \{x/b, y/b\}$.

σ is *more general* than γ :

there exists δ such that $\sigma\delta = \gamma$;

$$\delta = \{y/b\}.$$

Equational Problems - Syntactic Unification

Goal: *algorithm* that *unifies* terms.

Example:

- $h(\underbrace{x}, y, z) = h(\underbrace{f(w, w)}, f(x, x), f(y, y))$

Equational Problems - Syntactic Unification

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- $h(\underbrace{x}, y, z) = h(\underbrace{f(w, w)}, f(x, x), f(y, y))$
- $h(\underbrace{f(w, w)}, \underbrace{y}, z) =$
 $h(f(w, w), \underbrace{f(f(w, w), f(w, w))}, f(y, y))$, partial solution:
 $\{x/f(w, w)\}$

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 $h(f(w, w), \underbrace{f(f(w, w), f(w, w))}, f(y, y)),$ partial solution:
 $\{x/f(w, w)\}$

- $h(f(w, w), f(f(w, w), f(w, w)), \underbrace{z}) =$
 $h(f(w, w), f(f(w, w), f(w, w)), \underbrace{f(f(f(w, w), f(w, w)), f(f(w, w), f(w, w)))},$
partial solution: $\{x/f(w, w), y/f(f(w, w), f(w, w))\}$

Equational Problems - Syntactic Unification

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 $h(f(w, w), \underbrace{f(f(w, w), f(w, w))}, f(y, y)),$ partial solution:
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- $h(f(w, w), f(f(w, w), f(w, w)), \underbrace{z}) =$
 $h(f(w, w), f(f(w, w), f(w, w)), \underbrace{f(f(f(w, w), f(w, w)), f(f(w, w), f(w, w)))},$
partial solution: $\{x/f(w, w), y/f(f(w, w), f(w, w))\}$
- $h(f(w, w), f(f(w, w), f(w, w)), f(f(f(w, w), f(w, w)), f(f(w, w), f(w, w)))) =$
 $h(f(w, w), f(f(w, w), f(w, w)), f(f(f(w, w), f(w, w)), f(f(w, w), f(w, w)))),$
solution: $\{x/f(w, w), y/f(f(w, w), f(w, w)), z/f(f(f(w, w), f(w, w)), f(f(w, w), f(w, w)))\}.$

Interesting questions:

- Correctness and Completeness.
- Complexity.
- With adequate data structures, there are linear solutions (Huet, Martelli-Montanari 1976, Petterson-Wegman 1978).

Syntactic unification is of type *unary* and linear.

When operators have algebraic equational properties, the problem is not as simple.

Example: for f commutative (C), $f(x, y) \approx f(y, x)$:

- $f(x, y) = f(a, b)$?

The unification problem is of type *finitary*.

When operators have algebraic equational properties, the problem is not as simple.

Example: for f commutative (C), $f(x, y) \approx f(y, x)$:

- $f(x, y) = f(a, b)$?
- Solutions: $\{x/a, y/b\}$ and $\{x/b, y/a\}$.

The unification problem is of type *finitary*.

Example: for f associative (A), $f(f(x, y), z) \approx f(x, f(y, z))$:

- $f(x, a) = f(a, x)$?

The unification problem is of type *infinitary*.

Example: for f associative (A), $f(f(x, y), z) \approx f(x, f(y, z))$:

- $f(x, a) = f(a, x)$?
- Solutions: $\{x/a\}, \{x/f(a, a)\}, \{x/f(a, f(a, a))\}, \dots$

The unification problem is of type *infinitary*.

Example: for f AC with *unity* (U), $f(x, e) \approx x$:

- $f(x, y) = f(a, b)$?

The unification problem is of type *finitary*.

Example: for f AC with *unity* (U), $f(x, e) \approx x$:

- $f(x, y) = f(a, b)$?
- Solutions: $\{x/e, y/f(a, b)\}$, $\{x/f(a, b), y/e\}$, $\{x/a, y/b\}$, and $\{x/b, y/a\}$.

The unification problem is of type *finitary*.

Example: for $f \in A$, and *idempotent* (I), $f(x, x) \approx x$:

- $f(x, f(y, x)) = f(f(x, z), x)$?

The unification problem is of type *zero* (Schmidt-Schauß 1986, Baader 1986).

Example: for f A, and *idempotent* (I), $f(x, x) \approx x$:

- $f(x, f(y, x)) = f(f(x, z), x)$?
- Solutions: $\{y/f(u, f(x, u)), z/u\}, \dots$

The unification problem is of type *zero* (Schmidt-Schauß 1986, Baader 1986).

Example: for $+$ AC, and h homomorphism (h),
 $h(x + y) \approx h(x) + h(y)$:

- $h(y) + a = y + z?$

The unification problem is of type *zero* and undecidable (Narendran 1996). The same happens for ACUh (Nutt 1990, Baader 1993).

Example: for $+$ AC, and h homomorphism (h),
 $h(x + y) \approx h(x) + h(y)$:

- $h(y) + a = y + z$?
- Solutions: $\{y/a, z/h(a)\}, \{y/h(a) + a, z/h^2(a)\}, \dots,$
 $\{y/h^k(a) + \dots + h(a) + a, z/h^{k+1}(a)\}, \dots$

The unification problem is of type *zero* and undecidable (Narendran 1996). The same happens for ACUh (Nutt 1990, Baader 1993).

Motivation

Synthesis on Unification modulo

Synthesis Unification modulo i

| | | Synthesis Unification modulo | | | |
|-----------|------------|------------------------------|----------|-------------|-----------------------------|
| Theory | Unif. type | Equality-checking | Matching | Unification | Related work |
| Syntactic | 1 | $O(n)$ | $O(n)$ | $O(n)$ | R65 MM76 PW78 |
| C | ω | $O(n^2)$ | NP-comp. | NP-comp. | BKN87 KN87 |
| A | ∞ | $O(n)$ | NP-comp. | NP-hard | M77 BKN87 |
| AU | ∞ | $O(n)$ | NP-comp. | decidable | M77 KN87 |
| AI | 0 | $O(n)$ | NP-comp. | NP-comp. | Klíma02 SS86 Baader86 |

Synthesis Unification modulo

| Synthesis Unification modulo | | | | | |
|------------------------------|------------|-------------------|----------|-------------|-----------------------|
| Theory | Unif. type | Equality-checking | Matching | Unification | Related work |
| AC | ω | $O(n^3)$ | NP-comp. | NP-comp. | BKN87 KN87 KN92 |
| ACU | ω | $O(n^3)$ | NP-comp. | NP-comp. | KN92 |
| AC(U)I | ω | - | - | NP-comp. | KN92 BMMO20 |
| D | ω | - | NP-hard | NP-hard | TA87 |
| ACh | 0 | - | - | undecidable | B93 N96 EL18 |
| ACUh | 0 | - | - | undecidable | B93 N96 |

Bindings and Nominal Syntax

Systems with bindings frequently appear in mathematics and computer science, but are not captured adequately in first-order syntax.

For instance, the formulas

$$\forall x_1, x_2 : x_1 + 1 + x_2 > 0 \quad \text{and} \quad \forall y_1, y_2 : 1 + y_2 + y_1 > 0$$

are not syntactically equal, but should be considered equivalent in a system with binding and AC operators.

The nominal setting extends first-order syntax, replacing the concept of syntactical equality by α -equivalence, which let us represent smoothly those systems.

Profiting from the nominal paradigm implies adapting basic notions (substitution, rewriting, equality) to it.

Atoms and Variables


Consider a set of variables $\mathbb{X} = \{X, Y, Z, \dots\}$ and a set of atoms $\mathbb{A} = \{a, b, c, \dots\}$.

Definition 1 (Nominal Terms)

Nominal terms are inductively generated according to the grammar:

$$s, t ::= a \mid \pi \cdot X \mid \langle \rangle \mid [a]t \mid \langle s, t \rangle \mid f t \mid f^{AC} t$$

where π is a permutation that exchanges a finite number of atoms.

To guarantee that AC function applications have at least two arguments, we have the notion of [well-formed terms](#) 

Freshness predicate

$a\#t$ means that if a occurs in t then it does so under an abstractor $[a]$.

A context is a set of constraints of the form $a\#X$. Contexts are denoted as Δ , Γ or ∇ .

An atom permutation π represents an exchange of a finite amount of atoms in \mathbb{A} and is presented by a list of swappings:

$$\pi = (a_1 \ b_1) :: \dots :: (a_n \ b_n) :: \textit{nil}$$

Examples of Permutation Actions

Permutations act on atoms and terms:

- $(a\ b) \cdot a = b$;
- $(a\ b) \cdot b = a$;
- $(a\ b) \cdot f(a, c) = f(b\ c)$;
- $(a\ b) :: (b\ c) \cdot [a]\langle a, c \rangle = (b\ c)[b]\langle b, c \rangle = [c]\langle c, b \rangle$.

Intuition Behind the Concepts

Two important predicates are the *freshness* predicate $\#$, and the *α -equality* predicate \approx_α .

- $a\#t$ means that if a occurs in t then it must do so under an abstractor $[a]$.
- $s \approx_\alpha t$ means that s and t are α -equivalent.

A *context* is a set of constraints of the form $a\#X$. Contexts are denoted by the letters Δ , ∇ or Γ .

Advantages of the name binding nominal approach

Freshness conditions $a\#s$, and atom permutations $\pi \cdot s$.

Example

β and η rules as nominal rewriting rules:

$$app\langle lam[a]M, N \rangle \rightarrow subs\langle [a]M, N \rangle \quad (\beta)$$

$$a\#M \vdash lam[a]app\langle M, a \rangle \rightarrow M \quad (\eta)$$

Some substitution rules:

$$b\#M \vdash subs\langle [b]M, N \rangle \rightarrow M$$

$$a\#N \vdash subs\langle [b]lam[a]M, N \rangle \rightarrow lam[a]sub\langle [b]M, N \rangle$$

$$c\#M, c\#N \vdash subs\langle [b]lam[a]M, N \rangle \rightarrow lam[c]sub\langle [b](a\ c) \cdot M, N \rangle$$

Advantages of the name binding nominal approach

- First-order terms with binders and *implicit* atom dependencies.
- Easy syntax to present *name binding* predicates as $a \in \text{FreeVar}(M)$, $a \in \text{BoundVar}([a]s)$, and operators as renaming: $(a\ b) \cdot s$.
- Built-in α -equivalence and first-order *implicit substitution*.
- Feasible syntactic equational reasoning: efficient equality-check, matching, and unification algorithms.

$$\frac{}{\Delta \vdash a \# \langle \rangle} (\# \langle \rangle)$$

$$\frac{}{\Delta \vdash a \# b} (\#atom)$$

$$\frac{(\pi^{-1}(a) \# X) \in \Delta}{\Delta \vdash a \# \pi \cdot X} (\#X)$$

$$\frac{}{\Delta \vdash a \# [a]t} (\#[a]a)$$

$$\frac{\Delta \vdash a \# t}{\Delta \vdash a \# [b]t} (\#[a]b)$$

$$\frac{\Delta \vdash a \# s \quad \Delta \vdash a \# t}{\Delta \vdash a \# \langle s, t \rangle} (\#pair)$$

$$\frac{\Delta \vdash a \# t}{\Delta \vdash a \# f t} (\#app)$$

Derivation Rules for alpha-Equivalence

$$\frac{}{\Delta \vdash \langle \rangle \approx_{\alpha} \langle \rangle} (\approx_{\alpha} \langle \rangle)$$

$$\frac{}{\Delta \vdash a \approx_{\alpha} a} (\approx_{\alpha} \text{atom})$$

$$\frac{\Delta \vdash s \approx_{\alpha} t}{\Delta \vdash fs \approx_{\alpha} ft} (\approx_{\alpha} \text{app})$$

$$\frac{\Delta \vdash s \approx_{\alpha} t}{\Delta \vdash [a]s \approx_{\alpha} [a]t} (\approx_{\alpha} [a]a)$$

$$\frac{\Delta \vdash s \approx_{\alpha} (a b) \cdot t, a \# t}{\Delta \vdash [a]s \approx_{\alpha} [b]t} (\approx_{\alpha} [a]b)$$

$$\frac{ds(\pi, \pi') \# X \subseteq \Delta}{\Delta \vdash \pi \cdot X \approx_{\alpha} \pi' \cdot X} (\approx_{\alpha} \text{var})$$

$$\frac{\Delta \vdash s_0 \approx_{\alpha} t_0, \Delta \vdash s_1 \approx_{\alpha} t_1}{\Delta \vdash \langle s_0, s_1 \rangle \approx_{\alpha} \langle t_0, t_1 \rangle} (\approx_{\alpha} \text{pair})$$

Additional Rule for alpha-Equivalence with C Functions

Let f be a C function symbol.

We add rule (\approx_α *c-app*) for dealing with C functions:

$$\frac{\Delta \vdash s_2 \approx_\alpha t_1 \quad \Delta \vdash s_1 \approx_\alpha t_2}{\Delta \vdash f^C \langle s_1, s_2 \rangle \approx_\alpha f^C \langle t_1, t_2 \rangle}$$

Additional Rule for alpha-Equivalence with AC Functions

Let f be an AC function symbol.

We add rule (\approx_α *ac-app*) for dealing with AC functions:

$$\frac{\Delta \vdash S_i(f^{AC} s) \approx_\alpha S_j(f^{AC} t) \quad \Delta \vdash D_i(f^{AC} s) \approx_\alpha D_j(f^{AC} t)}{\Delta \vdash f^{AC} s \approx_\alpha f^{AC} t}$$

$S_n(f^*)$ selects the n^{th} argument of the *flattened* subterm f^* .

$D_n(f^*)$ deletes the n^{th} argument of the *flattened* subterm f^* .

Derivation Rules as a Sequent Calculus

Deriving $\vdash \forall[a] \oplus \langle a, fa \rangle \approx_\alpha \forall[b] \oplus \langle fb, b \rangle$, where \oplus is C:

$$\begin{array}{c}
 \frac{}{a \approx_\alpha a} (\approx_\alpha \text{atom}) \quad \frac{}{fa \approx_\alpha fa} (\approx_\alpha \text{app}) \quad \frac{}{a \approx_\alpha a} (\approx_\alpha \text{atom}) \quad \frac{}{a \# b} (\# \text{atom})}{\frac{}{a \# fb} (\# \text{app})} \quad \frac{}{a \# b} (\# \text{atom})} \\
 \frac{}{\oplus \langle a, fa \rangle \approx_\alpha (a \ b) \cdot \oplus \langle fb, b \rangle} (\approx_\alpha \text{c-app}) \quad \frac{}{a \# \langle fb, b \rangle} (\# \text{app}) \quad \frac{}{a \# b} (\# \text{pair})}{\frac{}{a \# \oplus \langle fb, b \rangle} (\# \text{app})} (\approx_\alpha [a]b) \\
 \frac{}{[a] \oplus \langle a, fa \rangle \approx_\alpha [b] \oplus \langle fb, b \rangle} (\approx_\alpha \text{app})}{\forall[a] \oplus \langle a, fa \rangle \approx_\alpha \forall[b] \oplus \langle fb, b \rangle} (\approx_\alpha \text{app})
 \end{array}$$

Nominal C-unification

Nominal C-unification

Unification problem: $\langle \Gamma, \{s_1 \approx_\alpha? t_1, \dots, s_n \approx_\alpha? t_n\} \rangle$

Unification solution: $\langle \Delta, \sigma \rangle$, such that

- $\Delta \vdash \Gamma \sigma$;
- $\Delta \vdash s_i \sigma \approx_\alpha t_i \sigma, 1 \leq i \leq n$.

We introduced nominal (equality-check, matching) and unification algorithms that provide solutions given as triples of the form:

$$\langle \Delta, \sigma, FP \rangle$$

where FP is a set of fixed-point equations of the form $\pi \cdot X \approx_\alpha? X$.

This provides a finite representation of the **infinite** set of solutions that may be generated from such fixed-point equations.

Nominal C-unification

Fixed point equations such as $\pi \cdot X \approx_{\alpha}^? X$ may have **infinite** independent solutions.

For instance, in a signature in which \oplus and \star are C, the unification problem: $\langle \emptyset, \{(a \ b)X \approx_{\alpha}^? X\} \rangle$

has solutions: $\left\{ \begin{array}{l} \langle \{a\#X, b\#X\}, id \rangle, \\ \langle \emptyset, \{X/a \oplus b\} \rangle, \langle \emptyset, \{X/a \star b\} \rangle, \dots \\ \langle \{a\#Z, b\#Z\}, \{X/(a \oplus b) \oplus Z\} \rangle, \dots \\ \langle \emptyset, \{X/(a \oplus b) \star (b \oplus a)\} \rangle, \dots \end{array} \right.$

Issues Adapting First-Order to Nominal AC-Unification

We modified Stickel-Fages's seminal AC-unification algorithm to avoid mutual recursion and verified it in the PVS proof assistant.

We formalised the algorithm's termination, soundness, and completeness [AFSS22].

An Example

Let f be an AC function symbol. The solutions that come to mind when unifying:

$$f(X, Y) \approx? f(a, W)$$

are:

$$\{X \rightarrow a, Y \rightarrow W\} \text{ and } \{X \rightarrow W, Y \rightarrow a\}$$

Are there other solutions?

Yes!

For instance, $\{X \rightarrow f(a, Z_1), Y \rightarrow Z_2, W \rightarrow f(Z_1, Z_2)\}$ and $\{X \rightarrow Z_1, Y \rightarrow f(a, Z_2), W \rightarrow f(Z_1, Z_2)\}$.

Example

the **AC Step** for AC-unification.

How do we generate a complete set of unifiers for:

$$f(X, X, Y, a, b, c) \approx? f(b, b, b, c, Z)$$

Eliminate common arguments in the terms we are trying to unify.

Now, we must unify

$$f(X, X, Y, a) \approx? f(b, b, Z)$$

According to the number of times each argument appears, transform the unification problem into a linear equation on \mathbb{N} :

$$2X_1 + X_2 + X_3 = 2Y_1 + Y_2,$$

Above, variable X_1 corresponds to argument X , variable X_2 corresponds to argument Y , and so on.

Stickel-Fages AC-unification - building a basis of solutions

Generate a basis of solutions to the linear equation.

Table 1: Solutions for the Equation $2X_1 + X_2 + X_3 = 2Y_1 + Y_2$

| X_1 | X_2 | X_3 | Y_1 | Y_2 | $2X_1 + X_2 + X_3$ | $2Y_1 + Y_2$ |
|-------|-------|-------|-------|-------|--------------------|--------------|
| 0 | 0 | 1 | 0 | 1 | 1 | 1 |
| 0 | 1 | 0 | 0 | 1 | 1 | 1 |
| 0 | 0 | 2 | 1 | 0 | 2 | 2 |
| 0 | 1 | 1 | 1 | 0 | 2 | 2 |
| 0 | 2 | 0 | 1 | 0 | 2 | 2 |
| 1 | 0 | 0 | 0 | 2 | 2 | 2 |
| 1 | 0 | 0 | 1 | 0 | 2 | 2 |

Stickel-Fages AC-unification - associating new variables

Associate new variables with each solution.

Table 2: Solutions for the Equation $2X_1 + X_2 + X_3 = 2Y_1 + Y_2$

| X_1 | X_2 | X_3 | Y_1 | Y_2 | $2X_1 + X_2 + X_3$ | $2Y_1 + Y_2$ | New Variables |
|-------|-------|-------|-------|-------|--------------------|--------------|---------------|
| 0 | 0 | 1 | 0 | 1 | 1 | 1 | Z_1 |
| 0 | 1 | 0 | 0 | 1 | 1 | 1 | Z_2 |
| 0 | 0 | 2 | 1 | 0 | 2 | 2 | Z_3 |
| 0 | 1 | 1 | 1 | 0 | 2 | 2 | Z_4 |
| 0 | 2 | 0 | 1 | 0 | 2 | 2 | Z_5 |
| 1 | 0 | 0 | 0 | 2 | 2 | 2 | Z_6 |
| 1 | 0 | 0 | 1 | 0 | 2 | 2 | Z_7 |

Observing the previous Table, relate the “old” variables and the “new” ones:

$$X_1 \approx? Z_6 + Z_7$$

$$X_2 \approx? Z_2 + Z_4 + 2Z_5$$

$$X_3 \approx? Z_1 + 2Z_3 + Z_4$$

$$Y_1 \approx? Z_3 + Z_4 + Z_5 + Z_7$$

$$Y_2 \approx? Z_1 + Z_2 + 2Z_6$$

Decide whether we will include (set to 1) or not (set to 0) every “new” variable. Every “old” variable must be different than zero.

In our example, we have 2^7 possibilities of including/excluding the variables Z_1, \dots, Z_7 , but after observing that X_1, X_2, X_3, Y_1, Y_2 cannot be set to zero, only 69 cases remain.

Drop the cases where the variables representing constants or subterms headed by a different AC function symbol are assigned to more than one of the “new” variables.

For instance, the potential new unification problem

$$\{X_1 \approx^? Z_6, X_2 \approx^? Z_4, X_3 \approx^? f(Z_1, Z_4), \\ Y_1 \approx^? Z_4, Y_2 \approx^? f(Z_1, Z_6, Z_6)\}$$

should be discarded as the variable X_3 , which represents the constant a , cannot unify with $f(Z_1, Z_4)$.

Replace “old” variables by the original terms they substituted and proceed with the unification.

Some new unification problems may be unsolvable and **will be discarded later**. For instance:

$$\{X \approx? Z_6, Y \approx? Z_4, a \approx? Z_4, b \approx? Z_4, Z \approx? f(Z_6, Z_6)\}$$

In our example,

$$f(X, X, Y, a, b, c) \approx? f(b, b, b, c, Z)$$

the solutions are:

$$\left\{ \begin{array}{l} \sigma_1 = \{Y \rightarrow f(b, b), Z \rightarrow f(a, X, X)\} \\ \sigma_2 = \{Y \rightarrow f(Z_2, b, b), Z \rightarrow f(a, Z_2, X, X)\} \\ \sigma_3 = \{X \rightarrow b, Z \rightarrow f(a, Y)\} \\ \sigma_4 = \{X \rightarrow f(Z_6, b), Z \rightarrow f(a, Y, Z_6, Z_6)\} \end{array} \right\}$$

Adapting first-order AC-unification to nominal AC-unification

We found a loop while solving nominal AC-unification problems using Stickel-Fages' Diophantine-based algorithm.

For instance

$$f(X, W) \approx? f(\pi \cdot X, \pi \cdot Y)$$

Variables are associated as below:

U_1 is associated with argument X ,

U_2 is associated with argument W ,

V_1 is associated with argument $\pi \cdot X$, and

V_2 is associated with argument $\pi \cdot Y$.

Table of Solutions

The Diophantine equation associated is $U_1 + U_2 = V_1 + V_2$.

The table with the solutions of the Diophantine equations is shown below. The name of the new variables was chosen to make clearer the loop we will fall into.

Table 3: Solutions for the Equation $U_1 + U_2 = V_1 + V_2$

| U_1 | U_2 | V_1 | V_2 | $U_1 + U_2$ | $V_1 + V_2$ | New variables |
|-------|-------|-------|-------|-------------|-------------|---------------|
| 0 | 1 | 0 | 1 | 1 | 1 | Z_1 |
| 0 | 1 | 1 | 0 | 1 | 1 | W_1 |
| 1 | 0 | 0 | 1 | 1 | 1 | Y_1 |
| 1 | 0 | 1 | 0 | 1 | 1 | X_1 |

$$\{X \approx^? X_1, W \approx^? Z_1, \pi \cdot X \approx^? X_1, \pi \cdot Y \approx^? Z_1\}$$

$$\{X \approx^? Y_1, W \approx^? W_1, \pi \cdot X \approx^? W_1, \pi \cdot Y \approx^? Y_1\}$$

$$\{X \approx^? Y_1 + X_1, W \approx^? W_1, \pi \cdot X \approx^? W_1 + X_1, \pi \cdot Y \approx^? Y_1\}$$

$$\{X \approx^? Y_1 + X_1, W \approx^? Z_1, \pi \cdot X \approx^? X_1, \pi \cdot Y \approx^? Z_1 + Y_1\}$$

$$\{X \approx^? X_1, W \approx^? Z_1 + W_1, \pi \cdot X \approx^? W_1 + X_1, \pi \cdot Y \approx^? Z_1\}$$

$$\{X \approx^? Y_1, W \approx^? Z_1 + W_1, \pi \cdot X \approx^? W_1, \pi \cdot Y \approx^? Z_1 + Y_1\}$$

$$\{X \approx^? Y_1 + X_1, W \approx^? Z_1 + W_1, \pi \cdot X \approx^? W_1 + X_1, \pi \cdot Y \approx^? Z_1 + Y_1\}$$

Seven branches are generated:

$$B1 - \{\pi \cdot X \approx^? X\}, \sigma = \{W \mapsto \pi \cdot Y\}$$

$$B2 - \sigma = \{W \mapsto \pi^2 \cdot Y, X \mapsto \pi \cdot Y\}$$

$$B3 - \{f(\pi^2 \cdot Y, \pi \cdot X_1) \approx^? f(W, X_1)\}, \sigma = \{X \mapsto f(\pi \cdot Y, X_1)\}$$

B4 - No solution

B5 - No solution

$$B6 - \sigma = \{W \mapsto f(Z_1, \pi \cdot X), Y \mapsto f(\pi^{-1} \cdot Z_1, \pi^{-1} \cdot X)\}$$

$$B7 - \{f(\pi \cdot Y_1, \pi \cdot X_1) \approx^? f(W_1, X_1)\},$$

$$\sigma = \{X \mapsto f(Y_1, X_1), W \mapsto f(Z_1, W_1), Y \mapsto f(\pi^{-1} \cdot Z_1, \pi^{-1} \cdot Y_1)\}$$



Focusing on **Branch 7**, notice that the problem before the AC Step and the problem after the AC Step and instantiating the variables are, respectively:

$$P = \{f(X, W) \approx? f(\pi \cdot X, \pi \cdot Y)\}$$




$$P_1 = \{f(X_1, W_1) \approx? f(\pi \cdot X_1, \pi \cdot Y_1)\}$$

Issues Adapting First-Order to Nominal AC-Unification

An Algorithm for Nominal AC-Matching

Nominal AC-matching is matching in the nominal setting in the presence of associative-commutative function symbols.

We proposed (to the best of our knowledge) the first nominal AC-matching algorithm, and formalised it in the PVS proof assistant ([AFFKS23] )

From unification to matching using protected variables

Given an algorithm of unification, one can adapt it by adding as a parameter a set of *protected variables* \mathcal{X} , which cannot be instantiated.

The adapted algorithm can then be used for:

- **Unification** - By putting $\mathcal{X} = \emptyset$.
- **Matching** - By putting \mathcal{X} as the set of variables in the right-hand side.
- **α -Equivalence** - By putting \mathcal{X} as the set of variables that appear in the problem.

We modify our first-order AC-unification formalisation to obtain a formalised algorithm for nominal AC-matching.

The algorithm is recursive and needs to keep track of



- the current context Γ ,
- the equational constraints we must unify P ,
- the substitution σ computed so far,
- the set of variables V that are/were in the problem, and
- the set of protected variables \mathcal{X} .



Hence, it's input is a quintuple $\langle \Gamma, P, \sigma, V, \mathcal{X} \rangle$.

Set of protected variables for matching problems

We assume the input satisfies $\text{Vars}(\text{rhs}(P)) \subseteq \mathcal{X}$ (notice that to obtain a nominal AC-unification algorithm, we would have to eliminate this hypothesis from the proofs).

The output is a list of solutions, each of the form $\langle \Gamma_1, \sigma_1 \rangle$.

The AC part of the algorithm (`ACMatch` ) is handled by function `applyACStep` , which relies on two functions: `solveAC` and `instantiateStep`.

- `solveAC`  builds the linear Diophantine equational system associated with the AC-matching equational constraint, generates the basis of solutions, and uses these solutions to generate the new AC-matching equational constraints.
- `instantiateStep`  instantiates the moderated variables that it can.



Idea: for the particular case of matching (unlike unification) all the new moderated variables introduced by `solveAC` are instantiated by `instantiateStep`.

Hence, termination is much easier in nominal AC-matching than in first-order AC-unification.

$\nabla' \vdash \nabla \sigma$ denotes that $\nabla' \vdash a \# X \sigma$ holds for each $(a \# X) \in \nabla$.

$\nabla \vdash \sigma \approx_V \sigma'$ denotes that $\nabla \vdash X \sigma \approx_\alpha X \sigma'$ for all X in V . When V is the set of all variables \mathbb{X} , we write $\nabla \vdash \sigma \approx \sigma'$.

Our algorithm receives as input quintuples. Hence, to state the theorems of soundness and completeness, we need the definition of a solution $\langle \Delta, \delta \rangle$ to a quintuple $\langle \Gamma, P, \sigma, V, \mathcal{X} \rangle$.

Definition 2 (Solution for a Quintuple)

A solution to a quintuple $\langle \Gamma, P, \sigma, V, \mathcal{X} \rangle$ is a pair $\langle \Delta, \delta \rangle$, where the following conditions are satisfied:

1. $\Delta \vdash \Gamma \delta$.
2. if $a \#_? t \in P$ then $\Delta \vdash a \# t \delta$.
3. if $t \approx_? s \in P$ then $\Delta \vdash t \delta \approx_\alpha s \delta$.
4. there exists λ such that $\Delta \vdash \lambda \circ \sigma \approx_V \delta$.
5. $\text{dom}(\delta) \cap \mathcal{X} = \emptyset$.

Note that if $\langle \Delta, \delta \rangle$ is a solution of $\langle \Gamma, \emptyset, \sigma, \mathbb{X}, \mathcal{X} \rangle$ this corresponds to the notion of $\langle \Delta, \delta \rangle$ being an instance of $\langle \Gamma, \sigma \rangle$ that does not instantiate variables in \mathcal{X} .

Theorem 3 (Soundness for AC-Matching)

Let the pair $\langle \Gamma_1, \sigma_1 \rangle$ be an output of $ACMatch(\langle \emptyset, \{t \approx? s\}, id, Vars(t, s), Vars(s) \rangle)$.

If $\langle \Delta, \delta \rangle$ is an instance of $\langle \Gamma_1, \sigma_1 \rangle$ that does not instantiate the variables in s , then

$\langle \Delta, \delta \rangle$ is a solution to $\langle \emptyset, \{t \approx? s\}, id, \mathbb{X}, Vars(s) \rangle$.

An interpretation of the previous Theorem is that if $\langle \Delta, \delta \rangle$ is an AC-matching instance to one of the outputs of `ACMatch`, then $\langle \Delta, \delta \rangle$ is an AC-matching solution to the original problem.

Theorem 4 (Completeness for AC-Matching)

Suppose that $\langle \Delta, \delta \rangle$ is a solution to $\langle \emptyset, \{t \approx? s\}, id, \mathbb{X}, Vars(s) \rangle$, that $\delta \subseteq V$ and that $Vars(\Delta) \subseteq V$.

Then, there exists

$$\langle \Gamma, \sigma \rangle \in ACMatch(\langle \emptyset, \{t \approx? s\}, id, V, Vars(s) \rangle)$$

such that $\langle \Delta, \delta \rangle$ is an instance (restricted to the variables of V) of $\langle \Gamma, \sigma \rangle$ that does not instantiate the variables of s .

An interpretation of the previous Theorem is that if $\langle \Delta, \delta \rangle$ is an AC-matching solution to the initial problem, then $\langle \Delta, \delta \rangle$ is an AC-matching instance of one of the outputs of `ACMatch`.

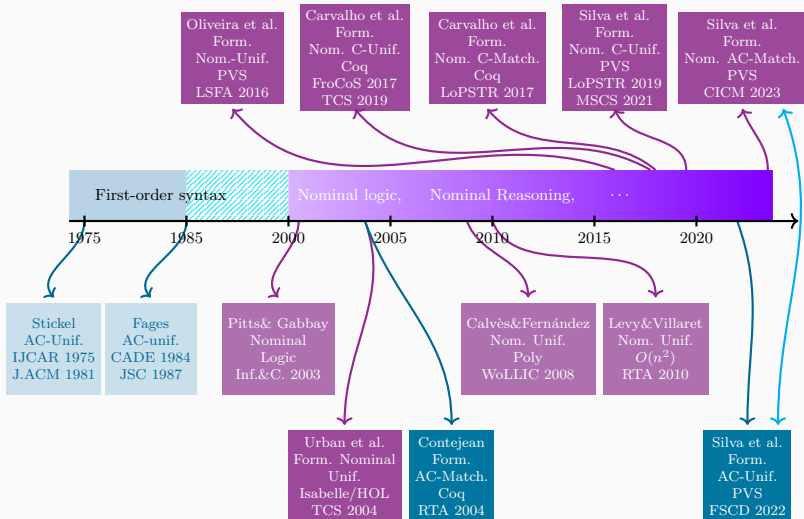
Formalisation Nominal AC-matching - The hypotheses on variables

The hypotheses $\delta \subseteq V$ and $Vars(\Delta) \subseteq V$ are just a technicality that was put to guarantee that the new variables introduced by the algorithm in the AC-part do not clash with the variables in $dom(\delta)$ or in the terms in $im(\delta)$ or in $Vars(\Delta)$.

Synthesis on Nominal Equational Modulo

Synthesis on Nominal Equational Modulo

Timeline on the formalisation of nominal equational reasoning



Synthesis of results on Nominal Unification Modulo

| Synthesis Unification Nominal Modulo | | | | | |
|--------------------------------------|------------|-------------------|---------------|-------------|---|
| Theory | Unif. type | Equality-checking | Matching | Unification | Related work |
| \approx_α | 1 | $O(n \log n)$ | $O(n \log n)$ | $O(n^2)$ | UPG04 LV10 CF08 CF10 LSFA2015 |
| C | ∞ | $O(n^2 \log n)$ | NP-comp. | NP-comp. | LOPSTR2017 FroCoS2017 TCS2019 LOPSTR2019 MSCS2021 |
| A | ∞ | $O(n \log n)$ | NP-comp. | NP-hard | LSFA2016 TCS2019 |
| AC | ω | $O(n^3 \log n)$ | NP-comp. | NP-comp. | LSFA2016 TCS2019 CICM2023 |

Also:

- [Overlaps in Nominal Rewriting](#) [LSFA 2015]
- [Nominal Narrowing](#) [FSCD 2016]
- [Nominal Intersection Types](#) [TCS 2018]
- [Nominal Disequations](#) [LSFA 2019]
- Nominal Syntax with [Permutation Fixed Points](#) [LMCS2020]

Work in Progress and Future Work



Removing the hypotheses $\delta \subseteq V$ and $\text{Vars}(\Delta) \subseteq V$ in the statement of completeness.

Table 4: Quantitative Data.




| Theory | Theorems | TCCs | Size (.pvs) | Size (.prf) | Size (%) |
|-----------------|----------|------|-------------|-------------|----------|
| [AFFKS23] | 6 | 4 | 2.8 kB | 0.02 MB | < 1% |
| unification_alg | 11 | 19 | 6.9 kB | 2.1 MB | 9% |
| ac_step | 45 | 11 | 15.8 kB | 1.6 MB | 7% |
| inst_step | 75 | 17 | 20.3 kB | 2 MB | 9% |
| aux_unification | 140 | 52 | 44.9 kB | 6.9 MB | 30% |
| Diophantine | 77 | 44 | 23.5 kB | 1 MB | 4% |
| unification | 119 | 13 | 28.0 kB | 1.7 MB | 8% |
| fresh_subs | 37 | 5 | 10.9 kB | 0.6 MB | 3% |
| substitution | 166 | 34 | 30.1 kB | 2.5 MB | 11% |
| equality | 83 | 20 | 15.1 kB | 1.6 MB | 7% |
| freshness | 15 | 10 | 4.5 kB | 0.1 MB | < 1% |
| terms | 147 | 53 | 29.1 kB | 1.1 MB | 5 % |
| atoms | 14 | 3 | 3.7 kB | 0.03 MB | < 1 % |
| list | 265 | 113 | 54.9 kB | 1.4 MB | 6 % |
| Total | 1200 | 398 | 290.5 kB | 22.6MB | 100% |

The approach in progress is similar to the one applied for removing variables to the first-order AC-unification algorithm formalization in [FSCD2022] .



- 🔍 Study how to avoid the circularity in nominal AC-unification.
 - ❓ How circularity enriches the set of computed solutions?
 - ❓ Under which conditions can circularity be avoided?
- 🔗 Consider the alternative approach to AC-unification proposed by Boudet, Contejean and Devie [BCD90, Bou93], which was used to define AC higher-order pattern unification.
- 🔗 Explore the connection between nominal and higher-order patterns to obtain a nominal AC-unification algorithm.

Thank you!

-  Mauricio Ayala-Rincón, Maribel Fernández, Gabriel Ferreira Silva, and Daniele Nantes Sobrinho, *A Certified Algorithm for AC-Unification*, Formal Structures for Computation and Deduction, FSCD 2022 (2022).
-  Alexandre Boudet, Evelyne Contejean, and Hervé Devie, *A New AC Unification Algorithm with an Algorithm for Solving Systems of Diophantine Equations*, Proceedings of the Fifth Annual Symposium on Logic in Computer Science, LICS, 1990.
-  Alexandre Boudet, *Competing for the AC-Unification Race*, J. of Autom. Reasoning (1993).