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- $\mathcal{O}:$ a set of syntactic objects.
 - Typically, expressions (e.g., terms, formulas, ...) in some formal language.
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 - Typically, variable substitutions.

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 $\mu(O)$ is called an instance of the object O with respect to $\mu \in \mathcal{M}.$

A base relation \mathcal{B} is a binary reflexive relation on \mathcal{O} .

An object $G \in \mathcal{O}$ is a generalization of the object $O \in \mathcal{O}$ with respect to \mathcal{B} and \mathcal{M} (briefly, $\mathcal{B}_{\mathcal{M}}$ -generalization) if $\mathcal{B}(\mu(G), O)$ holds for some mapping $\mu \in \mathcal{M}$.



A preference relation \mathcal{P} : a binary reflexive transitive relation on \mathcal{O} .

 $\mathcal{P}(O_1, O_2)$ indicates that the object O_1 is preferred over O_2 . It induces an equivalence relation $\equiv_{\mathcal{P}}$:

$$O_1 \equiv_{\mathcal{P}} O_2 \text{ iff } \mathcal{P}(O_1, O_2) \text{ and } \mathcal{P}(O_2, O_1).$$

The base relation \mathcal{B} and the preference relation \mathcal{P} are consistent on \mathcal{O} with respect to \mathcal{M} or, shortly, \mathcal{M} -consistent, if the following holds:

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If G₁ is a B_M-generalization of O and P(G₁, G₂) holds for some G₂, then G₂ is also a B_M-generalization of O.



We consider only consistent base and preference relations.

An object G is called a most \mathcal{P} -preferred common $\mathcal{B}_{\mathcal{M}}$ -generalization of objects $O_1, \ldots, O_n, n \ge 2$ if

- **G** is a $\mathcal{B}_{\mathcal{M}}$ -generalization of each O_i , and
- for any G' that is also a $\mathcal{B}_{\mathcal{M}}$ -generalization of each O_i , if $\mathcal{P}(G', G)$, then G' $\equiv_{\mathcal{P}} G$.
 - (If G' is \mathcal{P} -preferred over G, then they are \mathcal{P} -equivalent.)

 $(\mathcal{B}_{\mathcal{M}}, \mathcal{P})$ -generalization problem over \mathcal{O} :

 $\begin{array}{lll} \mbox{Given:} & \mbox{Objects } O_1, \ldots, O_n \in \mathcal{O}, \, n \geq 2. \\ \mbox{Find:} & \mbox{An object } G \in \mathcal{O} \mbox{ that is a most } \mathcal{P}\mbox{-preferred} \\ & \mbox{common } \mathcal{B}_{\mathcal{M}}\mbox{-generalization of } O_1, \ldots, O_n. \end{array}$

 $(\mathcal{B}_{\mathcal{M}}, \mathcal{P})$ -generalization problem over \mathcal{O} :

 $\begin{array}{lll} \mbox{Given:} & \mbox{Objects } \mathsf{O}_1,\ldots,\mathsf{O}_n\in\mathcal{O},\,n\geq 2. \\ \mbox{Find:} & \mbox{An object } \mathsf{G}\in\mathcal{O} \mbox{ that is a most } \mathcal{P}\mbox{-preferred} \\ & \mbox{common } \mathcal{B}_{\mathcal{M}}\mbox{-generalization of } \mathsf{O}_1,\ldots,\mathsf{O}_n. \end{array}$

This problem may have zero, one, or more solutions.

Two reasons of zero solutions:

- either the objects O₁,..., O_n have no common B_M-generalization at all (i.e, O₁,..., O_n are not generalizable), or
- they are generalizable but have no most *P*-preferred common *B_M*-generalization.

To characterize "informative" sets of possible solutions, we introduce two notions: \mathcal{P} -complete and \mathcal{P} -minimal complete sets of common $\mathcal{B}_{\mathcal{M}}$ -generalizations of multiple objects.

A set of objects $\mathcal{G} \subseteq \mathcal{O}$ is called a \mathcal{P} -complete set of common $\mathcal{B}_{\mathcal{M}}$ -generalizations of the given objects $O_1, \ldots, O_n, n \ge 2$, if the following properties are satisfied:

- **Soundness:** every $G \in \mathcal{G}$ is a common $\mathcal{B}_{\mathcal{M}}$ -generalization of O_1, \ldots, O_n , and
- **Completeness:** for each common $\mathcal{B}_{\mathcal{M}}$ -generalization G' of O_1, \ldots, O_n there exists $G \in \mathcal{G}$ such that $\mathcal{P}(G, G')$.

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The set \mathcal{G} is called \mathcal{P} -minimal complete set of common $\mathcal{B}_{\mathcal{M}}$ -generalizations of O_1, \ldots, O_n and is denoted by $\operatorname{mcsg}_{\mathcal{B}_{\mathcal{M}}, \mathcal{P}}(O_1, \ldots, O_n)$ if, in addition, the following holds:

■ **Minimality:** no distinct elements of \mathcal{G} are \mathcal{P} -comparable: if $G_1, G_2 \in \mathcal{G}$ and $\mathcal{P}(G_1, G_2)$, then $G_1 = G_2$.

The type of the $(\mathcal{B}_{\mathcal{M}}, \mathcal{P})$ -generalization problem between generalizable objects $O_1, \ldots, O_n \in \mathcal{O}$ is

- **unitary** (1): if $mcsg_{\mathcal{B}_{\mathcal{M}},\mathcal{P}}(O_1,\ldots,O_n)$ is a singleton,
- finitary (ω): if mcsg_{B_M,P}(O₁,...,O_n) is finite and contains at least two elements,
- infinitary (∞): if $mcsg_{\mathcal{B}_{\mathcal{M}},\mathcal{P}}(O_1,\ldots,O_n)$ is infinite,
- nullary (0): if mcsg_{BM,P}(O₁,...,O_n) does not exist (i.e., minimality and completeness contradict each other).

The type of $(\mathcal{B}_{\mathcal{M}}, \mathcal{P})$ -generalization over \mathcal{O} is

- **unitary** (1): if each (*B*_{*M*}, *P*)-generalization problem between generalizable objects from *O* is unitary,
- finitary (ω): if each (B_M, P)-generalization problem between generalizable objects from O is unitary or finitary, and there exists a finitary problem,
- infinitary (∞): if each (B_M, P)-generalization problem between generalizable objects from O is unitary, finitary, or infinitary, and there exists an infinitary problem,
- **nullary** (0): if there exists a nullary $(\mathcal{B}_{\mathcal{M}}, \mathcal{P})$ -generalization problem between generalizable objects from \mathcal{O} .

Let $\mathcal{S} \subseteq \mathcal{O}$.

S-fragment of the generalization problem:

■ the given objects $O_1, ..., O_n$ are restricted to belong to S: $O_1 \in S, ..., O_n \in S$

S-**variant** of the generalization problem:

• the desired generalizations G are restricted to belong to S:

 $\mathsf{G}\in\mathcal{S}$

It also makes sense to consider an S_1 -variant of an S_2 -fragment of the problem, where S_1 and S_2 are not necessarily the same.

Interesting questions:

- Generalization type: What is the (*B*_M, *P*)-generalization type over *O*?
- Generalization algorithm/procedure: How to compute (or enumerate) a complete set of generalizations (preferably, mcsg_{BM,P}) for objects from O.

Some concrete cases: FOSG

First-order syntactic generalization:

Generic	Concrete (FOSG)
Ø	First-order terms
\mathcal{M}	First-order substitutions
B	\doteq (syntactic equality)
\mathcal{P}	\succeq : $s \succeq t$ iff $s \doteq t\sigma$ for some σ
$\equiv_{\mathcal{P}}$	Equi-generality: \succeq and \preceq
Туре	Unitary
Algorithm	[Plotkin70, Reynolds70, Huet76]

Example

 $\mathsf{mcsg}(f(a, f(a, c)), f(b, f(b, c))) = \{f(x, f(x, c))\}.$

Some concrete cases: FOEG

First-order equational generalization modulo an equational theory E:

Generic	Concrete (FOEG)
Ø	First-order terms
\mathcal{M}	First-order substitutions
B	\doteq_{E} (equality modulo the theory <i>E</i>)
\mathcal{P}	\succeq_{E} : $s \succeq_{E} t$ iff $s \doteq_{E} t\sigma$ for some σ .
$\equiv_{\mathcal{P}}$	Equi-generality modulo E: \succeq_E and \preceq_E
Туре	Depends on a particular E
Algorithm	Depends on a particular E

Some concrete cases: FOEG, AC

First-order equational generalization, the AC case:

Generic	Concrete (FOEG: AC)
Ø	First-order terms
\mathcal{M}	First-order substitutions
B	\doteq_{AC} (equality modulo AC)
\mathcal{P}	\succeq_{AC} : $s \succeq_{AC} t$ iff $s \doteq_{AC} t\sigma$ for some σ .
$\equiv_{\mathcal{P}}$	Equi-generality modulo AC: \succeq_{AC} and \preceq_{AC}
Туре	Finitary
Algorithm	[Alpuente et al, 2014]

Example

If f is an AC symbol, then

 $\mathsf{mcsg}(f(f(a,a),b),\ f(f(b,b),a)) = \{f(f(x,x),y),\ f(f(x,a),b)\}.$

Some concrete cases: FOEG, Abs

First-order equational generalization, the absorption case.

Axioms: f(x,e) = e, f(e,x) = e.

Generic	Concrete (FOEG: Abs)
O	First-order terms
\mathcal{M}	First-order substitutions
B	\doteq_{Abs} (equality modulo Abs)
\mathcal{P}	\succeq_{Abs} : $s \succeq_{Abs} t$ iff $s \doteq_{Abs} t\sigma$ for some σ .
$\equiv_{\mathcal{P}}$	Equi-generality modulo Abs: \succeq_{Abs} and \preceq_{Abs}
Туре	Infinitary
Algorithm	Andres Gonzalez et al, ongoing work

Some concrete cases: FOEG, GSC

First-order equational generalization for a ground subterm-collapsing theory, axiomatized with two equalities f(a) = a, f(b) = b.

Generic	Concrete (FOEG: GSC)
O	First-order terms
\mathcal{M}	First-order substitutions
${\mathcal B}$	\doteq_{GSC} (equality modulo GSC)
${\cal P}$	\succeq_{GCS} : $s \succeq_{GSC} t$ iff $s \doteq_{GSC} t\sigma$ for some σ .
$\equiv_{\mathcal{P}}$	Equi-generality modulo GSC: \succeq_{GSC} and \preceq_{GSC}
Туре	Nullary
Algorithm	TBD

Example

The problem $a \triangleq_{GSC}^{?} b$ has no mcsg: the complete set of generalizations contains an infinite chain $x \preceq_{GCS} f(x) \preceq_{GCS} f(f(x)) \cdots$.

Summary for some FOEG theory types

- A, C, AC: finitary [Alpuente et al, 2014]
- U^{>1}, (ACU)^{>1}, (CU)^{>1}, (AU)^{>1}, (AU)(CU): nullary Their single-symbol versions as well as linear variants are finitary [Cerna&Kutsia, FSCD'20];
- I, AI, CI: infinitary [Cerna&Kutsia, TOCL, 2020];
- (UI)^{>1}, (AUI)^{>1}, (CUI)^{>1}, (ACUI)^{>1}, semirings: nullary [Cerna 2020];
- Commutative theories: unitary [Baader 1991].

Some concrete cases: FOVG

First-order variadic generalization:

Generic	Concrete (FOVG)
O	Variadic terms and their sequences
\mathcal{M}	Substitutions (for terms and for sequences)
B	\doteq (syntactic equality)
\mathcal{P}	\succeq : $s \succeq t$ iff $s \doteq t\sigma$ for some σ .
$\equiv_{\mathcal{P}}$	Equi-generality: \succeq and \preceq
Туре	Finitary (also for the rigid variant)
Algorithm	[Kutsia et al, 2014]

Example

mcsg(g(f(a), f(a)), g(f(a), f)) for the unrestricted case is

 $\{g(f(a),f(X)), \ g(f(X,Y),f(X)), \ g(f(X,Y),f(Y))\}.$

For the rigid variant, it is $\{g(f(a), f(X))\}$.

Some concrete cases: FOCG

First-order clausal generalization.

Generic	Concrete (FOCG)
Ø	First-order clauses
\mathcal{M}	First-order substitutions
B	\subseteq
\mathcal{P}	\succeq_{CI} : $s \succeq_{CI} t$ iff $s \supseteq t\sigma$ for some σ .
	($t \sigma$ -subsumes s)
$\equiv_{\mathcal{P}}$	Equi-generality modulo CI: \succeq_{CI} and \preceq_{CI}
Туре	Unitary
Algorithm	[Plotkin, 1970]

Example

Let
$$C_1 := p(a) \leftarrow q(a), q(b)$$
 $C_2 := p(b) \leftarrow q(b), q(x)$

 $G_1 := p(y) \leftarrow q(y), q(b) \qquad G_2 := p(y) \leftarrow q(y), q(b), q(z)$

Then G_1 and G_2 both are lggs of C_1 and C_2 , and $G_1 \equiv_{\mathcal{P}} G_2$.

Some concrete cases: HOG $_{\alpha\beta\eta}$

Higher-order $\alpha\beta\eta$ -generalization

Generic	Concrete (HOG $_{\alpha\beta\eta}$)
O	Simply-typed λ terms
\mathcal{M}	Higher-order substitutions
B	$pprox$ (equality modulo $lphaeta\eta$)
\mathcal{P}	ightharpoonrightarrow tsizes tsizes tsizes tsizes to the substitution σ.
$\equiv_{\mathcal{P}}$	Equi-general (\succsim and \precsim) modulo $lphaeta\eta$
Туре	nullary in general [Buran&Cerna, to appear]
	unitary for the TMS variant [Cerna&Kutsia, 2019]
Algorithm	TMS variant [Cerna&Kutsia, 2019],
	patterns [Baumgartner et al, 2017]

Some concrete cases: HOG $_{\alpha\beta\eta}$

Example

Various top-maximal shallow lggs for

 $\lambda x. f(h(g(g(x))), h(g(x)), a)$ and $\lambda x. f(g(g(x)), g(x), h(a))$

Projection-based:

 $\lambda x.f(X(h(g(g(x))),g(g(x))),X(h(g(x)),g(x)),X(a,h(a))),$

Common subterms:

 $\lambda x.f(X(g(g(x))), X(g(x))), Z(a)),$

Patterns:

 $\lambda x.f(X(x), Y(x), Z).$

Description logics.

Decidable fragments of first-order logic.

The basic syntactic building blocks in DLs:

 \blacksquare (primitive) concept names P, Q, \dots (unary predicates),

 \blacksquare role names r, q, \dots (binary predicates),

 \blacksquare individual names a, b, \dots (constants).

. . .

Starting from these constructions, complex concept descriptions and roles are built using constructors, which determine the expressive power of the DL.

$$\begin{aligned} \mathcal{EL}: \quad C, D &:= P \mid \top \mid C \sqcap D \mid \exists r.C. \\ \mathcal{FLE}: \quad C, D &:= P \mid \top \mid C \sqcap D \mid \exists r.C \mid \forall r.C. \end{aligned}$$

An interpretation $\mathcal{I} = (\Delta_\mathcal{I}, \cdot^\mathcal{I})$ consists of

- \blacksquare a non-empty set $\Delta^{\mathcal{I}}$, called the interpretation domain, and
- **\blacksquare** a mapping $\cdot^{\mathcal{I}}$, called the extension mapping.

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The mapping maps

• every concept name P to a set $P^{\mathcal{I}} \subseteq \Delta_{\mathcal{I}}$,

every role name r to a binary relation $r^{\mathcal{I}} \subseteq \Delta_{\mathcal{I}} \times \Delta_{\mathcal{I}}$.

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For the other concept descriptions:

$$T^{\mathcal{I}} = \Delta_{\mathcal{I}},$$

$$(C \sqcap D)^{\mathcal{I}} = C^{\mathcal{I}} \cap D^{\mathcal{I}},$$

$$(\exists r.C)^{\mathcal{I}} = \{ d \in \Delta_{\mathcal{I}} \mid \exists e. (d, e) \in r^{\mathcal{I}} \land e \in C^{\mathcal{I}} \},$$

$$(\forall r.C)^{\mathcal{I}} = \{ d \in \Delta_{\mathcal{I}} \mid \forall e. (d, e) \in r^{\mathcal{I}} \Rightarrow e \in C^{\mathcal{I}} \}.$$

A concept description *C* is subsumed by *D*, written $C \sqsubseteq D$, if $C^{\mathcal{I}} \subseteq D^{\mathcal{I}}$ holds for all interpretations \mathcal{I} .

 $C \equiv D$: if C and D subsume each other.

A concept description D is called a least common subsumer of C_1 and C_2 , if

 \blacksquare $C_1 \sqsubseteq D$ and $C_2 \sqsubseteq D$ and

If there exists D' such that $C_1 \sqsubseteq D'$ and $C_2 \sqsubseteq D'$, then $D \sqsubseteq D'$.

A concept description C is subsumed by D, written $C \sqsubseteq D$, if $C^{\mathcal{I}} \subseteq D^{\mathcal{I}}$ holds for all interpretations \mathcal{I} .

 $C \equiv D$: if C and D subsume each other.

A concept description D is called a least common subsumer of C_1 and C_2 , if

 \blacksquare $C_1 \sqsubseteq D$ and $C_2 \sqsubseteq D$ and

If there exists D' such that $C_1 \sqsubseteq D'$ and $C_2 \sqsubseteq D'$, then $D \sqsubseteq D'$.

The problem of computing the least common subsumer of two or more concept descriptions is a version of the problem of computing generalizations in DLs.

DLs \mathcal{EL} and \mathcal{FLE} :

Generic	Concrete (DL)
Ø	Concept descriptions
\mathcal{M}	Contains only the identity mapping
B	
\mathcal{P}	
$\equiv_{\mathcal{P}}$	$\equiv: \sqsubseteq$ and \supseteq
Туре	Unitary
Algorithm	[Baader et al, 1999]

Example (EL)

 $C = P \sqcap \exists r. (\exists r. (P \sqcap Q) \sqcap \exists s. Q) \sqcap \exists r. (P \sqcap \exists s. P)$

 $D = \exists r.(P \sqcap \exists r.P \sqcap \exists s.Q)$

 $LCS(C,D) = \exists r.(\exists r.P \sqcap \exists s.Q) \sqcap \exists r.(P \sqcap \exists s.\top)$

Some concrete cases: ProxGen

Quantitative generalization modulo fuzzy proximity relations:

Generic	Concrete (ProxGen)
Ø	First-order terms
\mathcal{M}	First-order substitutions
B	$pprox_{\mathcal{R},\lambda}$ (approximate equality)
\mathcal{P}	\succeq : $s \succeq t$ iff $s \doteq t\sigma$ for some σ .
$\equiv_{\mathcal{P}}$	Equi-generality: \succeq and \preceq
Туре	Finitary
Algorithm	[Kutsia&Pau, 2022]

Some concrete cases: ProxGen

If we defined \mathcal{P} as $\succeq_{\mathcal{R},\lambda}$ where $s \succeq_{\mathcal{R},\lambda} t$ iff $s \approx_{\mathcal{R},\lambda} t\sigma$ for some σ , then it would not be consistent with \mathcal{B} .

If $\mathcal{R}(a, b) = 0.7$ and $\mathcal{R}(b, c) = 0.7$, then both a and b are $(\mathcal{R}, 0.7)$ -generalizations of a and b, but c is not.

But taking $\mathcal{P} = \succeq_{\mathcal{R},\lambda}$, we would get that *c* is also a $(\mathcal{R}, 0.7)$ -generalization of *a* and *b*, which is wrong.

Some more concrete cases

Clausal generalization:

• based on relative θ -subsumption,

based on T-implication.

Order-sorted generalization:

syntactic,

modulo equational theories.

Variadic generalization:

- for commutative (orderless) theories,
- for term-graphs.

Generalization in the description logic \mathcal{EL} :

an approach that allows variables in the generalization

Some more concrete cases

Nominal generalization:

allowing finitely many atoms
 using atom variables
 ...

Higher-order generalization:

- simple types, modulo $\alpha\beta\eta$ and equational theories,
- let polymorphic lambda-calculus ($\lambda 2$),
- second order variadic terms,
- **.**..

Applications

Typical applications fall into one of the following areas:

- learning and reasoning,
- synthesis and exploration,
- analysis and repair.

- Studying the influence of the signature of equational theories on the generalization type
- Investigating methods of combining generalization algorithms over disjoint equational theories
- Characterization of equational theories exhibiting similar behavior and properties for generalization problems

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- Studying the influence of the preference relation choice on the type and solution set of generalization problems
- Combination with other kind of generalization and abstraction techniques + new applications

Reference

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