# Process Calculi A Brief, Gentle Introduction

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A part of this set of slides was originally produced by Jiri Srba, and makes part of the course material for the book

# Reactive Systems: Modelling, Specification and Verification by L. Aceto, A. Ingolfsdottir, K. G. Larsen and J. Srba URL: http://rsbook.cs.aau.dk

I have adapted them for the purposes of this talk.

# 🦉 / Outline

# Introduction

# CCS

Introduction to CCS Syntax of CCS Semantics of CCS Value Passing CCS Semantic Equivalences Strong Bisimilarity Weak Bisimilarity

# The $\pi$ -calculus

Informal Introduction The  $\pi$ -calculus, formally





Characterization of a Classical Program

Program transforms an input into an output.

 Denotational semantics: a meaning of a program is a partial function

 $states \hookrightarrow states$ 

- Nontermination is bad!
- In case of termination, the result is unique.

Is this all we need?



What about:

- Operating systems?
- Communication protocols?
- Control programs?
- Mobile phones?
- Vending machines?





### Characterization of a Reactive System

Reactive System is a system that computes by reacting to stimuli from its environment.

Key Issues:

- communication and interaction
- parallelism

Nontermination is good!

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#### Questions

- How can we develop (design) a system that "works"?
- How do we analyze (verify) such a system?

#### Fact of Life

Even short parallel programs may be hard to analyze.



#### Conclusion

We need formal/systematic methods (tools), otherwise ...

- Intel's Pentium-II bug in floating-point division unit
- Ariane-5 crash due to a conversion of 64-bit real to 16-bit integer
- Mars Pathfinder
- ...



# Classical vs. Reactive Computing

	Classical	Reactive/Parallel
interaction	no	yes
nontermination	undesirable	often desirable
unique result	yes	no
semantics	$states \hookrightarrow states$	? < 51



# How to Model Reactive Systems

#### Question

What is the most abstract view of a reactive system (process)?



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#### Answer

A process performs an action and becomes another process.



# Definition

A labelled transition system (LTS) is a triple  $(Proc, Act, \{\stackrel{a}{\longrightarrow} | a \in Act\})$  where

- *Proc* is a set of states (or processes),
- Act is a set of labels (or actions), and
- for every  $a \in Act$ ,  $\xrightarrow{a} \subseteq Proc \times Proc$  is a binary relation on states called the transition relation.

We will use the infix notation  $s \xrightarrow{a} s'$  meaning that  $(s, s') \in \xrightarrow{a}$ .

Sometimes we distinguish the initial (or start) state.



LTS explicitly focuses on interaction.

LTS can also describe:

- sequencing (a; b)
- choice (nondeterminism) (a + b)
- limited notion of parallelism (by using interleaving) (a || b)



# Definition

A binary relation  $\mathcal{R}$  on a set A is a subset of  $A \times A$ .

 $\mathcal{R} \subseteq A \times A$ 

Sometimes we write  $x \mathcal{R} y$  instead of  $(x, y) \in \mathcal{R}$ .

#### Properties

- $\mathcal{R}$  is reflexive if  $(x, x) \in \mathcal{R}$  for all  $x \in A$
- $\mathcal{R}$  is symmetric if  $(x, y) \in \mathcal{R}$  implies  $(y, x) \in R$  for all  $x, y \in A$
- $\mathcal{R}$  is transitive if  $(x, y) \in \mathcal{R}$  and  $(y, z) \in \mathcal{R}$  implies that  $(x, z) \in \mathcal{R}$  for all  $x, y, z \in A$

We assume usual definitions of closures (reflexive, symmetric, transitive).

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# <sup>7</sup> Labelled Transition Systems – Notation

Let 
$$(Proc, Act, \{\stackrel{a}{\longrightarrow} | a \in Act\})$$
 be an LTS.

- we extend  $\stackrel{a}{\longrightarrow}$  to the elements of  $Act^{*}$ 

• 
$$\longrightarrow = \bigcup_{a \in Act} \xrightarrow{a}$$

$$\bullet \longrightarrow^*$$
 is the reflexive and transitive closure of  $\cdot$ 

• 
$$s \xrightarrow{a}$$
 and  $s \xrightarrow{a}$ 

reachable states

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#### Syntax

unknown entity

programming language

??? CCS

# Semantics

known entity

what (denotational) or how (operational) it computes Labelled Transition Systems



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Labelled Transition Systems



Process calculus called "Calculus of Communicating Systems".

### Insight of Robin Milner (1989)

Concurrent (parallel) processes have an algebraic structure.

$$P_1 op P_2 \Rightarrow P_1 op P_2$$



# Basic Principle

- Define a few atomic processes (modeling the simplest process behavior).
- Obtained the process behavior from simple ones).

#### Example

- $lacksymbol{0}$  atomic instruction: assignment (e.g. x:=2 and x:=x+2)
- 2 new operators:
  - sequential composition  $(P_1; P_2)$
  - parallel composition  $(P_1 \parallel P_2)$
  - E.g. (x:=1 || x:=2); x:=x+2; (x:=x-1 || x:=x+5) is a

process.

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- Nil (or 0) process (the only atomic process)
- action prefixing (a.P)
- names and recursive definitions (<sup>def</sup>=)
- nondeterministic choice (+)



#### This is Enough to Describe Sequential Processes

Any finite LTS can be (up to isomorphism) described by using the operations above.



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- parallel composition ( || ) (synchronous communication between two components = handshake synchronization)
- restriction  $((\nu a_1, \ldots, a_n)P)$ Alternative notation:  $P \smallsetminus L$ , with  $L = \{a_1, \ldots, a_n\}$
- relabelling (P[f])



# CCS Basics (Parallelism and Renaming)

- parallel composition ( || ) (synchronous communication between two components = handshake synchronization)
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Assigning names to processes (as in procedures) allows us to give recursive definitions of process behaviors.

Some examples:

- $Clock \stackrel{\text{def}}{=} tick.Clock$
- $CM \stackrel{\text{def}}{=} coin. \overline{coffee}. CM$
- $VM \stackrel{\text{def}}{=} coin. \overline{item}. VM$
- $CTM \stackrel{\text{def}}{=} coin.(\overline{coffee}.CTM + \overline{tea}.CTM)$

• 
$$CS \stackrel{\text{def}}{=} \overline{pub}.\overline{coin}.coffee.CS$$

•  $SmUni \stackrel{\text{def}}{=} (\nu coin, coffee)(CM \parallel CS)$ 



# Let

• A be a set of channel names (e.g. *tea*, *coffee*)

# • $\mathcal{L} = \mathcal{A} \cup \overline{\mathcal{A}}$ be a set of labels where

- A = {ā | a ∈ A} (A are called names and A are called co-names
  by convention ā = a
- $Act = \mathcal{L} \cup \{\tau\}$  is the set of actions where
  - $\tau$  is the internal or silent action

(e.g.  $\tau$ , *tea*, *coffee* are actions)



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# Definition of CCS (expressions)

$$P := K$$

$$\alpha.P$$

$$\sum_{i \in I} P_i$$

$$P_1 \parallel P_2$$

$$(\nu a_1, \dots, a_n)P$$

$$P[f]$$

process constants  $(K \in \mathcal{K})$ prefixing  $(\alpha \in Act)$ summation (I is an arbitrary index set) parallel composition restriction ( $\{a_1, \ldots, a_n\} \subseteq \mathcal{A}$ ) relabelling ( $f : Act \to Act$ ) such that •  $f(\tau) = \tau$ •  $f(\overline{a}) = \overline{f(a)}$ 

The set of all terms generated by the abstract syntax is called CCS process expressions (and denoted by  $\mathcal{P}$ ).

#### Notation

$$P_1 + P_2 = \sum_{i \in \{1,2\}} P_i$$

 $Nil = 0 = \sum_{i \in \emptyset} P_i$ 



#### Precedence

- 1 restriction and relabelling (tightest binding)
- 2 action prefixing
- 8 parallel composition
- **4** summation

# Example: $R + a.P \parallel b.Q \smallsetminus L$ means $R + ((a.P) \parallel (b.(Q \smallsetminus L))).$



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# Definition of CCS (defining equations)

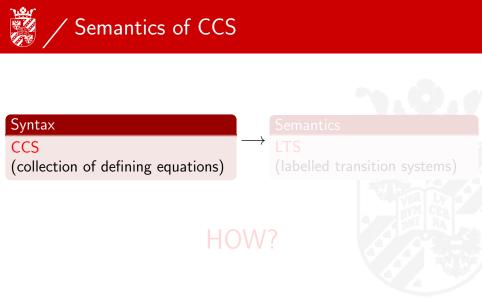
# CCS program

A collection of defining equations of the form

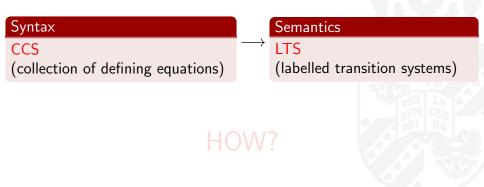
$$K \stackrel{\text{def}}{=} P$$

where  $K \in \mathcal{K}$  is a process constant and  $P \in \mathcal{P}$  is a CCS process expression.

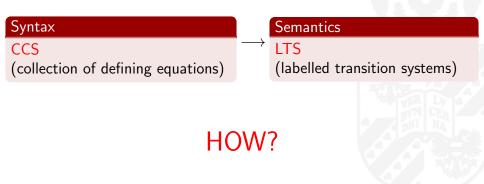
- Only one defining equation per process constant.
- Recursion is allowed: e.g.  $A \stackrel{\text{def}}{=} \overline{a}.A \parallel A$ .













# Structural Operational Semantics for CCS

# Structural Operational Semantics (SOS) – G. Plotkin 1981

Small-step operational semantics where the behaviour of a system is inferred using syntax driven rules.

Given a collection of CCS defining equations, we define the following LTS (*Proc*, *Act*,  $\{\stackrel{a}{\longrightarrow} | a \in Act\}$ ):

- $Proc = \mathcal{P}$  (the set of all CCS process expressions)
- $Act = \mathcal{L} \cup \{\tau\}$  (the set of all CCS actions including  $\tau$ )
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- transition relation is given by SOS rules of the form:

RULE 
$$\frac{premises}{conclusion}$$
 conditions



$$\begin{array}{ll} \operatorname{ACT} & \overline{\alpha.P \xrightarrow{\alpha} P} & \operatorname{SUM}_{j} & \overline{\sum_{i \in I} P_{i} \xrightarrow{g}} j \in I \\ \\ \operatorname{COM1} & \frac{P \xrightarrow{\alpha} P'}{P \| Q \xrightarrow{\alpha} P' \| Q} & \operatorname{COM2} & \frac{Q \xrightarrow{\alpha} Q'}{P \| Q \xrightarrow{\alpha} P \| Q'} \\ \\ \operatorname{COM3} & \frac{P \xrightarrow{a} P' Q \xrightarrow{\overline{\alpha}} Q'}{P \| Q \xrightarrow{\overline{\gamma}} P' \| Q'} \\ \\ \operatorname{RES} & \frac{P \xrightarrow{\alpha} P'}{P \smallsetminus L \xrightarrow{\alpha} P' \searrow L} & \alpha, \overline{\alpha} \notin L & \operatorname{REL} & \frac{P \xrightarrow{\alpha} P'}{P[f] \xrightarrow{f(\alpha)} P'[f]} \\ \\ \operatorname{CON} & \frac{P \xrightarrow{\alpha} P'}{K \xrightarrow{\alpha} P'} & K \stackrel{\text{def}}{=} P \end{array}$$



Let  $A \stackrel{\text{def}}{=} a.A$ . Then

 $\left( (A \parallel \overline{a}.Nil) \parallel b.Nil \right) [c/a] \stackrel{c}{\longrightarrow} \left( (A \parallel \overline{a}.Nil) \parallel b.Nil \right) [c/a].$ 





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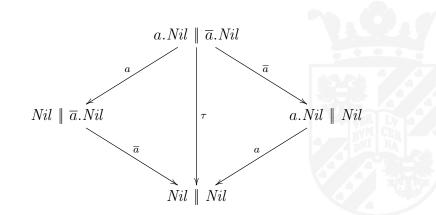


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### Main Idea

Handshake synchronization is extended with the possibility to exchange integer values.

 $\overline{pay(6)}$ .Nil || pay(x). $\overline{save(x/2)}$ .Nil





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#### Parametrized Process Constants

For example:  $Bank(total) \stackrel{\text{def}}{=} save(x).Bank(total + x).$ 



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$$Nil \parallel Nil \parallel Bank(103)$$

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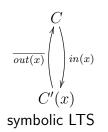
# From Value Passing CCS to Standard CCS

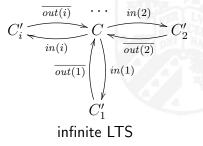
# Value Passing CCS

$$C \stackrel{\text{def}}{=} in(x).C'(x)$$
$$C'(x) \stackrel{\text{def}}{=} \overline{out(x)}.C$$

# Standard CCS

$$C \stackrel{\text{def}}{=} \sum_{i \in \mathbb{N}} in(i).C_i$$
$$C'_i \stackrel{\text{def}}{=} \overline{out(i)}.C$$







CCS can simulate a computation of any Turing machine.

#### Remark

Hence CCS is as expressive as any other programming language but its use is to rather describe the behaviour of reactive systems than to perform specific calculations.



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Implementation	Specification	
$CM \stackrel{\text{def}}{=} coin. \overline{coffee}. CM$ $CS \stackrel{\text{def}}{=} \overline{pub}. \overline{coin}. coffee. CS$	$Spec \stackrel{\mathrm{def}}{=} \overline{pub}.Spec$	
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Are the processes $Uni$ and $S$	Spec behaviorally equivalent?	



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Question	
Are the processes $Uni$ and $Spec$ behaviorally equivalent?	

 $Uni \equiv Spec$ 



# What should a reasonable behavioral equivalence satisfy?

- abstract from states (consider only the behavior actions)
- abstract from nondeterminism
- abstract from internal behavior

#### What else should a reasonable behavioural equivalence satisfy?

- reflexivity  $P \equiv P$  for any process P
- transitivity  $Spec_0 \equiv Spec_1 \equiv Spec_2 \equiv \cdots \equiv Impl$  gives that  $Spec_0 \equiv Impl$
- symmetry  $P \equiv Q$  iff  $Q \equiv P$

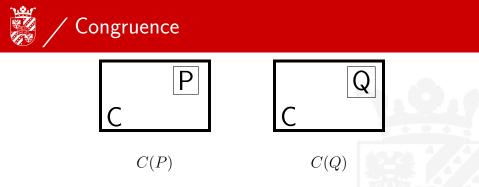


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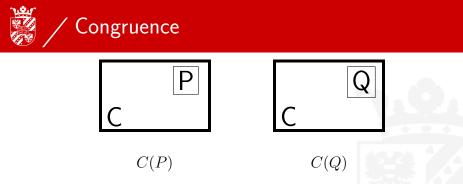


 We would like "equal" processes P and Q to "behave the same" under any context C(·).

A context is a process with a hole.
 When the hole is filled in with a process P, we obtain another process (usually noted C(P) or C[P]).

Congruence Property

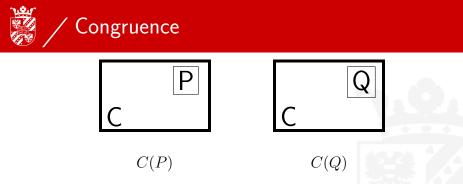
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Let 
$$(Proc, Act, \{\stackrel{a}{\longrightarrow} | a \in Act\})$$
 be an LTS.

Trace Set for  $s \in Proc$ 

$$Traces(s) = \{ w \in Act^* \mid \exists s' \in Proc. \ s \xrightarrow{w} s' \}$$

Let  $s \in Proc$  and  $t \in Proc$ .

Trace Equivalence

We say that s and t are trace equivalent  $(s \equiv_t t)$  if and only if Traces(s) = Traces(t)



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#### Trace Equivalence

We say that s and t are trace equivalent  $(s \equiv_t t)$  if and only if Traces(s) = Traces(t)



# Main Idea

Two processes are behaviorally equivalent if and only if an external observer cannot tell them apart.



# Let $(Proc, Act, \{\stackrel{a}{\longrightarrow} | a \in Act\})$ be an LTS.

## Strong Bisimulation

A binary relation  $\mathcal{R} \subseteq Proc \times Proc$  is a strong bisimulation iff whenever  $(s,t) \in \mathcal{R}$  then for each  $a \in Act$ :

• if 
$$s \xrightarrow{a} s'$$
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#### Theorem

 $\sim$  is an equivalence (reflexive, symmetric and transitive)

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 $s \sim t$  if and only if for each  $a \in Act$ :

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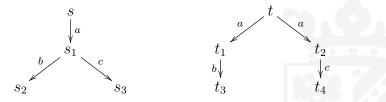
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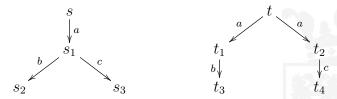
- Enumerate all binary relations and show that none of them at the same time contains (s, t) and is a strong bisimulation. (Expensive: 2<sup>|Proc|<sup>2</sup></sup> relations.)
- Make certain observations which will enable to disqualify many bisimulation candidates in one step.
- Use game characterization of strong bisimilarity.





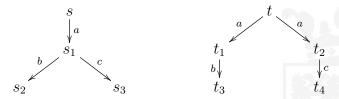
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#### Theorem

Let P and Q be CCS processes such that  $P \sim Q$ . Then

- $\alpha.P \sim \alpha.Q$  for each action  $\alpha \in Act$
- $P + R \sim Q + R$  and  $R + P \sim R + Q$  for each CCS process R
- $P \mid R \sim Q \mid R$  and  $R \mid P \sim R \mid Q$  for each CCS process R
- $(\nu a) P \sim (\nu a) Q$  for any a.



#### Following Properties Hold for any CCS Processes P, Q and R

- $P + Q \sim Q + P$
- $\bullet \ P \parallel Q \sim Q \parallel P$
- $P + Nil \sim P$
- $P \parallel Nil \sim P$
- $(P+Q)+R \sim P+(Q+R)$
- $\bullet \ (P \parallel Q) \parallel R \sim P \parallel (Q \parallel R)$





$$B_0^1 \stackrel{\text{def}}{=} in.B_1^1$$
$$B_1^1 \stackrel{\text{def}}{=} \overline{out}.B_0^1$$

$$B_0^n \stackrel{\text{def}}{=} in.B_1^n$$
  

$$B_i^n \stackrel{\text{def}}{=} in.B_{i+1}^n + \overline{out}.B_{i-1}^n \quad \text{for } 0 < i < n$$
  

$$B_n^n \stackrel{\text{def}}{=} \overline{out}.B_{n-1}^n$$

#### Example: $B_0^2 \sim B_0^1 \| B_0^1$



Jorge A. Pérez (Groningen)

#### An Introduction to Process Calculi



# Buffer of Capacity 1Buffer of Capacity n $B_0^1 \stackrel{\text{def}}{=} in.B_1^1$ $B_0^n \stackrel{\text{def}}{=} in.B_1^n$ $B_1^1 \stackrel{\text{def}}{=} \overline{out}.B_0^1$ $B_0^n \stackrel{\text{def}}{=} in.B_1^n$ $B_n^n \stackrel{\text{def}}{=} \overline{out}.B_0^n$ $B_n^n \stackrel{\text{def}}{=} \overline{out}.B_{n-1}^n$

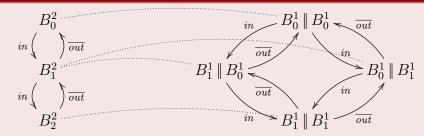
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#### Theorem

For all natural numbers n:

$$B_0^n \sim \underbrace{B_0^1 \parallel B_0^1 \parallel \cdots \parallel B_0^1}_{n \text{ times}}$$

#### Proof.

The co-inductive proof method: to show bisimilarity, show an appropriate strong bisimulation.

Construct the following binary relation where  $i_1, i_2, \ldots, i_n \in \{0, 1\}$ .

$$\mathcal{R} = \{ \left( B_i^n, \ B_{i_1}^1 \, \| \, B_{i_2}^1 \, \| \, \cdots \, \| \, B_{i_n}^1 \right) \mid \sum_{j=1}^n i_j = i \}$$

•  $(B_0^n, B_0^1 || B_0^1 || \cdots || B_0^1) \in \mathcal{R}$ 

•  $\mathcal{R}$  is strong bisimulation



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- $\left(B_0^n, B_0^1 \| B_0^1 \| \cdots \| B_0^1\right) \in \mathcal{R}$
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#### Properties of $\sim$

- an equivalence relation
- the largest strong bisimulation
- a congruence
- enough to prove some natural rules like
  - $P \parallel Q \sim Q \parallel P$
  - $P \parallel Nil \sim P$
  - $\bullet \ (P \, \| \, Q) \, \| \, R \sim Q \, \| \, (P \, \| \, R)$
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Should we look any further???



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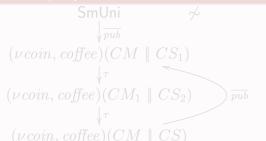
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Does  $a.\tau.Nil \sim a.Nil$  hold?

#### Problem

Strong bisimilarity does not abstract away from au actions.

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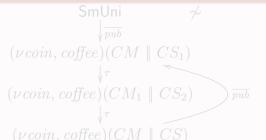
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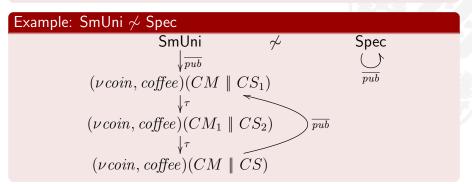


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Let 
$$(Proc, Act, \{\stackrel{a}{\longrightarrow} | a \in Act\})$$
 be an LTS such that  $\tau \in Act$ .

#### Definition of Weak Transition Relation

Below,  $\circ$  stands for function composition.

$$\stackrel{a}{\Longrightarrow} = \begin{cases} (\stackrel{\tau}{\longrightarrow})^* \circ \stackrel{a}{\longrightarrow} \circ (\stackrel{\tau}{\longrightarrow})^* & \text{if } a \neq \tau \\ (\stackrel{\tau}{\longrightarrow})^* & \text{if } a = \tau \end{cases}$$

What does  $s \stackrel{a}{\Longrightarrow} t$  informally mean?

• If  $a \neq \tau$  then  $s \stackrel{a}{\Longrightarrow} t$  means that

from s we can get to t by doing zero or more  $\tau$  actions, followed by the action a, followed by zero or more  $\tau$  actions.

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 If a = τ then s <sup>τ</sup>→ t means that from s we can get to t by doing zero or more τ actions.



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#### Weak Bisimulation

A binary relation  $\mathcal{R} \subseteq Proc \times Proc$  is a weak bisimulation iff whenever  $(s,t) \in \mathcal{R}$  then for each  $a \in Act$  (including  $\tau$ ):

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Two processes  $p_1, p_2 \in Proc$  are weakly bisimilar  $(p_1 \approx p_2)$  if and only if there exists a weak bisimulation  $\mathcal{R}$  such that  $(p_1, p_2) \in \mathcal{R}$ .

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#### Properties of $\approx$

- an equivalence relation
- the largest weak bisimulation
- validates lots of natural laws, e.g.
  - $a.\tau.P \approx a.P$
  - $P + \tau . P \approx \tau . P$

• 
$$a.(P+\tau.Q) \approx a.(P+\tau.Q) + a.Q$$

- $P + Q \approx Q + P$   $P \parallel Q \approx Q \parallel P$   $P + Nil \approx P$  ...
- strong bisimilarity is included in weak bisimilarity ( $\sim\,\subseteq\,\approx$ )
- abstracts from au loops





#### Theorem

Let P and Q be CCS processes such that  $P \approx Q$ . Then

- $\alpha . P \approx \alpha . Q$  for each action  $\alpha \in Act$
- $P \mid R \approx Q \mid R$  and  $R \mid P \approx R \mid Q$  for each CCS process R
- $(\nu a) P \approx (\nu a)Q$  for each set of labels L.

What about choice?

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# 🎆 🖊 Outline

#### Introduction

#### CCS

Introduction to CCS Syntax of CCS Semantics of CCS Value Passing CCS Semantic Equivalences Strong Bisimilarity Weak Bisimilarity

#### The $\pi$ -calculus

Informal Introduction The  $\pi$ -calculus, formally



## 🕺 / A Calculus of Mobile Processes

Arguably, the  $\pi\text{-calculus}$  is the paradigmatic concurrent calculus

• Proposed by Milner, Parrow, and Walker in 1992. Developed significantly by Sangiorgi.

Interactive systems with dynamic connectivity (topology). A dual role:

- A model of networked computation: Exchanged messages which contain links referring to communication channels themselves
- A basic model of computation: Interaction as the primitive notion of concurrent computing (Just as the λ-calculus for functional computing)



- The theory of the π-calculus is richer than that of CCS. In some aspects, however, it is also more involved.
- We will overview this theory, contrasting it with CCS
- Hence, we present the  $\pi$ -calculus without going too much into technical details

### / Mobility as dynamic connectivity (1)

Towards the meaning of 'mobility':

• What kind of entity moves? In what space does it move?

Many possibilities—the two most relevant are:

- Processes move, in the virtual space of linked processes
- 2 Links move, in the virtual space of linked processes

Observe that

- A process' location is given by the links it has to other processes (think of your contacts in your mobile phone)
- Hence, the movement of a process can be represented by the movement of its links

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## Mobility as dynamic connectivity (2)

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• Economy, flexibility, and simplicity (at least wrt CCS)

...while models of higher-order concurrency stick to (1

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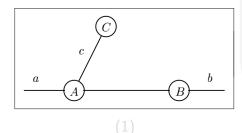
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## Dynamic connectivity in CCS is limited (1)

## What's the main difference of the $\pi$ -calculus wrt CCS? Dynamic connectivity.

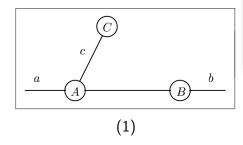
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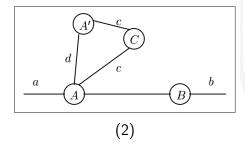
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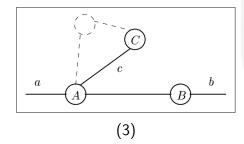


## / Dynamic connectivity in CCS is limited (3)

Suppose a CCS process  $S \stackrel{\text{def}}{=} (\nu x)(A \parallel C) \parallel B$ . Name *a* is free in *A*, while *b* is free in *B*.

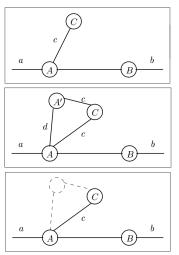
Suppose now that  $A \stackrel{\text{def}}{=} a.(\nu d)(A \parallel A') + c.A''.$ 

Finally, suppose that A' = c.0. Process A' then dies. Graphically:





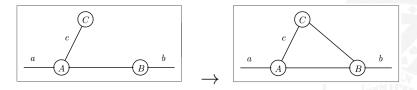
In CCS, links can proliferate and die:







However, new links between existing processes cannot be created. A transition such as

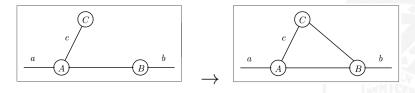


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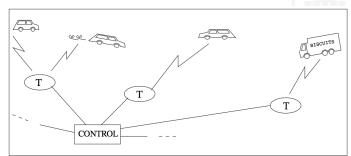
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# $\checkmark$ Mobile phones and cars (1)

#### A simple (yet probably outdated) application of mobility.

- Vehicles on the move; each connected to a transmitter 1
- Transmitters have fixed connections to a central control
- A vehicle can be switched to another transmitter
- Virtual movement of links between cars and transmitters

Before:



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#### An Introduction to Process Calculi

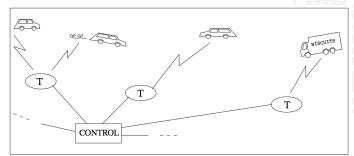


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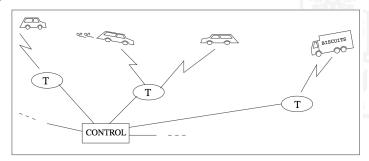


# Mobile phones and cars (2)

A simple (yet probably outdated) application of mobility.

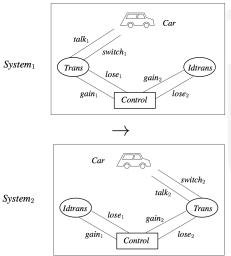
- Vehicles on the move; each connected to a transmitter T
- Transmitters have fixed connections to a central control
- A vehicle can be switched to another transmitter
- Virtual movement of links between cars and transmitters

#### After:





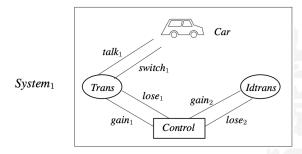
The handover protocol in the  $\pi$ -calculus, schematically:



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#### An Introduction to Process Calculi

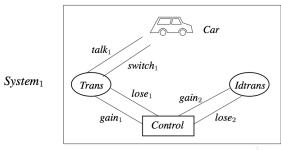




Main novelty: Communications may transmit names as messages

$$\begin{aligned} Trans\langle t, s, g, l \rangle &\stackrel{\text{def}}{=} t.Trans\langle t, s, g, l \rangle \ + \ l(t, s).\overline{s}\langle t, s \rangle.Idtrans\langle g, l \rangle \\ Idtrans\langle g, l \rangle &\stackrel{\text{def}}{=} g(t, s).Trans\langle t, s, g, l \rangle \end{aligned}$$





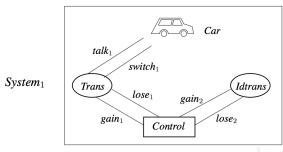
Control issues a new pair of links to be communicated to Car:

$$Control_1 \stackrel{\text{def}}{=} \overline{l_1} \langle t_2, s_2 \rangle . \overline{g_2} \langle t_2, s_2 \rangle . Control_2$$
$$Control_2 \stackrel{\text{def}}{=} \overline{l_2} \langle t_1, s_1 \rangle . \overline{g_1} \langle t_1, s_1 \rangle . Control_1$$

*Car* can either talk or switch to another transmitter (if requested):

$$Car\langle t,s \rangle \stackrel{\text{def}}{=} \overline{t}.Car\langle t,s \rangle + s(t,s).Car\langle t,s \rangle$$





The system is the restricted composition of the previous processes:

$$\begin{aligned} System_1 &\stackrel{\text{def}}{=} & (\nu t_1, s_1, g_1, l_1, t_2, s_2, g_2, l_2) \\ & (Car\langle t_1, s_1 \rangle \parallel Trans_1 \parallel Idtrans_2 \parallel Control_1) \end{aligned}$$

where we have use the abbreviations (i = 1, 2)

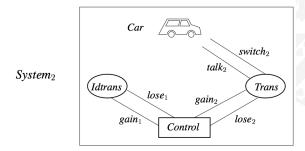
 $Trans_i \stackrel{\text{def}}{=} Trans\langle t_i, s_i, g_i, l_i \rangle \quad Idtrans_i \stackrel{\text{def}}{=} Idtrans\langle g_i, l_i \rangle$ 



The semantics of the  $\pi$ -calculus will allows to infer that  $System_1$  evolves to  $System_2$  where

$$\begin{aligned} System_2 & \stackrel{\text{def}}{=} & (\nu t_1, s_1, g_1, l_1, t_2, s_2, g_2, l_2) \\ & (Car\langle t_2, s_2 \rangle \parallel Trans_2 \parallel Idtrans_1 \parallel Control_2) \end{aligned}$$

(The process obtained from  $System_1$  by exchanging the indexes.)





We now formally introduce the  $\pi$ -calculus. Some highlights:

- The major novelty is name communication
- Dynamic connectivity formalized as scope extrusion
- A structural congruence relation



We use  $x, y, z, \ldots$  to range over  $\mathcal{N}$ , an infinite set of names.

The action prefixes of the  $\pi$ -calculus generalize the actions of CCS:

 $\begin{array}{rcl} \alpha & ::= & \overline{x} \langle y \rangle & \text{send name } y \text{ along } x \\ & & x(y) & \text{receive a name along } x \\ & & \tau & \text{unobservable action} \end{array}$ 

Brackets in  $\overline{x}\langle y \rangle$  represent a tuple of values.

- Above, monadic communication: exactly one name is sent.
- In polyadic communication more than one value may be sent.

P,Q



$$::=$$
0Inactive process $\alpha.P$ Prefix $P+P$ Sum $P \parallel Q$ Parallel composition $(\nu y)P$ Name Restriction $A\langle y_1, \ldots, y_n \rangle$ Identifier

We assume each identifier A is equipped with a recursive definition  $A(x_1, \ldots, x_n) \stackrel{\text{def}}{=} P$ , where  $i \neq j$  implies  $x_i \neq x_j$ .

- Restriction and input actions are name binders: In (vy)P and x(y).P name y is bound with scope P.
- In contrast, in  $\overline{x}\langle y\rangle$  name y is free.



A few intuitions:

• The syntax of processes is too concrete: syntactically different things that represent the same behavior. Examples:

$$egin{array}{lll} a(x).ar{b}\langle x
angle & \mbox{and} & a(y).ar{b}\langle y
angle \\ P\,\|\,Q & \mbox{and} & Q\,\|\,P \end{array}$$

[We often omit trailing 0s, and write  $\overline{b}\langle y \rangle$  instead of  $\overline{b}\langle y \rangle$ .0.]

- Structural congruence identifies processes which are "obviously the same" based on their structure
- In this sense, structural congruence will be stronger (that is, will equate less process) than any behavioral equivalence.



P and Q structurally congruent, written  $P \equiv Q$ , if we can transform one into the other by using the following equations:

- 1)  $\alpha$ -conversion: change of bound names
- **2** Laws for parallel composition:

$$P \parallel \mathbf{0} \equiv P$$

$$P \parallel Q \equiv Q \parallel P$$

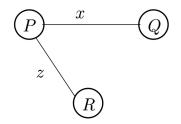
$$P \parallel (Q \parallel R) \equiv (P \parallel Q) \parallel R$$

S Law for recursive definitions: A⟨ỹ⟩ ≡ P{ỹ/x̂} if A(x̃) = P
4 Laws for restriction:

$$(\nu x)(P \parallel Q) \equiv P \parallel (\nu x)Q \quad \text{if } x \notin \mathsf{fn}(P)$$
$$(\nu x)\mathbf{0} \equiv \mathbf{0}$$
$$(\nu x)(P+Q) \equiv P + (\nu x)Q \quad \text{if } x \notin \mathsf{fn}(P)$$
$$(\nu x)(\nu y)P \equiv (\nu y)(\nu x)P$$

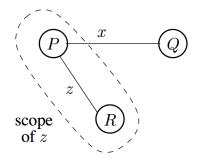


#### A process $P \parallel Q \parallel R$ . Name x is free in P and Q, while z is free in Q and R:





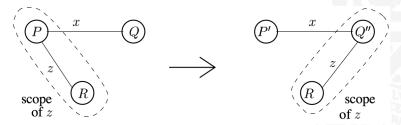
Suppose that z is restricted to P and R, while x is free in P and Q. That is, we have the process  $(\nu z)(P \parallel R) \parallel Q$ :



What happens if P wishes to send z to Q?



Suppose  $P = \overline{x}\langle z \rangle P'$ , with  $z \notin fn(P')$ . Suppose also Q = x(y).Q', with  $z \notin fn(Q')$ .



where  $Q'' = Q'\{z/y\}$ . We have graphically described the reduction  $(\nu z)(P \parallel R) \parallel Q \longrightarrow P' \parallel (\nu z)(R \parallel Q'')$ 

The above describes a movement of a way of accessing R (rather than a movement of R).



We present some simple examples of scope extrusion. We exploit three (informal) postulates for this:

1 A law for inferring interactions:

$$a(x).P \,\|\, \overline{a} \langle b \rangle.Q \stackrel{\tau}{\longrightarrow} P\{b/x\} \,\|\, Q$$

**2** Restrictions respect silent transitions:

$$P \xrightarrow{\tau} Q$$
 implies  $(\nu x)P \xrightarrow{\tau} (\nu x)Q$ 

Structurally congruent processes should have the same behavior.



# We use str. congruence to infer an interaction for the process $a(x).\overline{c}\langle x\rangle \parallel (\nu b)\overline{a}\langle b\rangle$

Since  $b \notin fn(a(x), \overline{c}\langle x \rangle)$ , we have

 $a(x).\overline{c}\langle x\rangle \parallel (\nu b)\overline{a}\langle b\rangle \equiv (\nu b)(a(x).\overline{c}\langle x\rangle \parallel \overline{a}\langle b\rangle)$ 

We can infer that

 $(\nu b)(a(x).\overline{c}\langle x\rangle \| \overline{a}\langle b\rangle) \xrightarrow{\tau} (\nu b)(\overline{c}\langle b\rangle \| \mathbf{0})$ 

because  $a(x).\overline{c}\langle x \rangle \parallel \overline{a}\langle b \rangle \stackrel{\tau}{\longrightarrow} \overline{c}\langle b \rangle \parallel \mathbf{0}$  is a valid interaction.

Removing 0, in general we have, for any  $b \notin fn(P)$ :

 $a(x).P \,\|\, (\nu b)\overline{a}\langle b\rangle.Q \stackrel{\tau}{\longrightarrow} (\nu b)(P \,\|\, Q\{b/x\})$ 

and the scope of b has moved from the right to the left.

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Consider the process:

$$P = (\nu z)((\overline{x}\langle y \rangle + z(w).\overline{w}\langle y \rangle) \parallel x(u).\overline{u}\langle v \rangle \parallel \overline{x}\langle z \rangle)$$

Observe:  $fn(P) = \{x, v, y\}$ ,  $bn(P) = \{z, w, u\}$ . Two possibilities:

Interaction among the first and second components:

$$P \xrightarrow{\tau} (\nu z)(\mathbf{0} \parallel \overline{u} \langle v \rangle \{ y/u \} \parallel \overline{x} \langle z \rangle)$$
  
=  $(\nu z)(\mathbf{0} \parallel \overline{y} \langle v \rangle \parallel \overline{x} \langle z \rangle) = P_1$ 

 $P\{y/u\}$  is the process P in which the free occurrences of name u have been substituted with y.

Interaction among the second and third components:

 $P \xrightarrow{\tau} (\nu z)((\overline{x}\langle y \rangle + z(w).\overline{w}\langle y \rangle) \parallel \overline{u}\langle v \rangle \{z/u\} \parallel \mathbf{0})$ =  $(\nu z)((\overline{x}\langle y \rangle + z(w).\overline{w}\langle y \rangle) \parallel \overline{z}\langle v \rangle \parallel \mathbf{0}) = P_2$ 

While  $P_1 \not\xrightarrow{\tau}$ , we do have  $P_2 \xrightarrow{\tau} (\nu z)(\overline{z}\langle y \rangle \parallel \mathbf{0} \parallel \mathbf{0}) \equiv (\nu z)\overline{z}\langle y \rangle$ 



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W

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## Process Calculi A Brief, Gentle Introduction

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