

**CONFORMAL METRICS AND RICCI TENSORS IN THE
PSEUDO-EUCLIDEAN SPACE**

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ABSTRACT. We consider constant symmetric tensors T on R^n , $n \geq 3$ and we study the problem of finding metrics \bar{g} conformal to the pseudo-Euclidean metric g such that $\text{Ric } \bar{g} = T$. We show that such tensors are determined by the diagonal elements and we obtain explicitly the metrics \bar{g} . As a consequence of these results we get solutions globally defined on R^n for the equation $-\varphi \Delta_g \varphi + n \|\nabla_g \varphi\|^2/2 + \lambda \varphi^2 = 0$. Moreover, we show that for certain unbounded functions \bar{K} defined on R^n , there are metrics conformal to the pseudo-Euclidean metric, with scalar curvature \bar{K} .

1. INTRODUCTION

Over the last few years several authors have considered the following problem:

Given a symmetric tensor of order two T defined on a manifold M^n , is there a Riemannian metric g such that $\text{Ric } g = T$? (P)

Finding solutions to this problem is equivalent to solving a nonlinear system of second-order partial differential equations. Deturck showed in [D1], that if $n \geq 3$, problem (P) has a local solution, when the given tensor T is nonsingular. Results on the existence and uniqueness of solutions for the problem (P), whenever M^n is a bi-dimensional manifold, can be found in [D2] and [CD1]. For compact manifolds, some results can be found in [DK], [H] and [X].

Cao and Deturck [CD2] studied the existence and uniqueness of global solutions in R^n and S^n , for rotationally symmetric and nonsingular tensors. In this case, they showed that problem (P) has a unique solution (up to homothety) and that for certain tensors in R^n , there is a complete metric g , globally defined on R^n , such that $\text{Ric } g = T$. On the sphere S^n , they proved some non-existence results and they found necessary conditions on a given tensor T , for the existence of a metric g on S^n satisfying $\text{Ric } g = T$.

There are two reasons for considering only nonsingular tensors T in [CD2]. First, uniqueness may fail. In the nonrotationally-symmetric context, there are examples where the solution of $\text{Ric } g = T$ is not unique (see [DK]). The second reason is that even local existence may fail (see [D2]).

Our main purpose in this work is to study problem (P) in R^n , $n \geq 3$, for constant symmetric tensors of the form

$$(1.1) \quad T = \sum_{i,j} \varepsilon_j c_{ij} dx_i \otimes dx_j \quad \text{with } c_{ij} \in R,$$

requiring the metric to be conformal to the pseudo-Euclidean metric.

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More precisely, we consider (R^n, g) with $n \geq 3$, $g_{ij} = \delta_{ij}\varepsilon_i$, $\varepsilon_i = \pm 1$, for all $1 \leq i, j \leq n$, where at least one eigenvalue ε_i is positive. We want to find metrics \bar{g} such that

$$(1.2) \quad \begin{cases} \bar{g} = \frac{1}{\varphi^2}g \\ \text{Ric } \bar{g} = T. \end{cases}$$

In Theorems 1.1 and 1.2, we treat the case of non-diagonal constant symmetric tensors T . In Theorem 1.1, we assume $\sum_i c_{ii} \neq 0$ and we give a necessary and sufficient condition for the existence of a metric \bar{g} satisfying (1.2). We show that such tensors, are determined by its diagonal elements c_{ii} , $1 \leq i \leq n$, which belong to a subset of R^n . This is a nonempty set obtained as the intersection of half spaces. For each such n -tuple $c = (c_{11}, \dots, c_{nn})$, there are at least 2 and generically 2^{n-1} tensors T for which there exists, up to homothety, two metrics \bar{g} satisfying $\text{Ric } \bar{g} = T$. In Theorem 1.2 we consider non-diagonal tensors T which satisfy $\sum_i c_{ii} = 0$. In Theorem 1.3 we treat the existence of metrics \bar{g} satisfying (1.2) for nonzero diagonal tensors T . The case $T \equiv 0$ is treated in Theorem 1.4. Moreover, in each of these theorems, the metrics are given explicitly and most of them are globally defined on R^n . However, we show that there are no complete metrics \bar{g} , conformal to g , such that $\text{Ric } \bar{g} = T$.

As a consequence of Theorem 1.1, 1.2 and 1.4 we find infinitely many explicit solutions of C^∞ class, defined on R^n for the equation

$$-\varphi \Delta_g \varphi + \frac{n}{2} \|\nabla_g \varphi\|^2 + \lambda \varphi^2 = 0$$

where Δ_g and ∇_g are the laplacian and gradient in the metric g respectively and the constant $\lambda \leq 0$ whenever g is the Euclidean metric and $\lambda \in R$ when g is the pseudo-Euclidean metric.

Finally, we show that for certain functions \bar{K} defined on R^n , there are metrics \bar{g} , conformal to g , with scalar curvature \bar{K} . These provide examples of unbounded functions which have positive answers to the following problem: Given a smooth function $\bar{K} : M \rightarrow R$ on a manifold (M, g) is there a metric \bar{g} conformal to g whose scalar curvature is \bar{K} ?

This problem has been studied by various authors. Particularly, when \bar{K} is a constant it is known as the Yamabe Problem. If $M^n = R^n$ with $n \geq 3$ and g is the Euclidean metric, various results can be found in [B], [K], [CN], [N], [DN], [LN] and in their references.

In order to state the results obtained in this paper, we need to introduce some notation. For a fixed pseudo-Euclidean metric $g_{ij} = \delta_{ij}\varepsilon_i$, $\varepsilon_i = \pm 1$, we consider the linear functions β_i , $1 \leq i \leq n$, defined for each $x = (x_1, \dots, x_n) \in R^n$ by

$$(1.3) \quad \beta_i(x) = (n-1)x_i - \sum_{k=1}^n x_k.$$

We consider the following subsets of R^n

$$(1.4) \quad D = \{x \in R^n; \varepsilon_j \beta_j(x) \geq 0 \forall j, 1 \leq j \leq n\}$$

$$(1.5) \quad L = \{x \in R^n; \varepsilon_j \beta_j(x) \leq 0 \forall j, 1 \leq j \leq n\}$$

and the hyperplanes

$$(1.6) \quad \pi_i = \{x \in R^n; \beta_i(x) = 0\}, \quad 1 \leq i \leq n.$$

D and L are nonempty subsets of R^n , obtained as the intersection of half-spaces of R^n , whose boundary is the union of the hyperplanes π_i . With this notation we can now state our results.

Theorem 1.1. *Let (R^n, g) be a pseudo-Euclidean space and let T be a non diagonal symmetric tensor as in (1.1) such that $\sum_i c_{ii} \neq 0$. Then there is a metric $\bar{g} = g/\varphi^2$ such that $\text{Ric } \bar{g} = T$, if and only if, $c = (c_{11}, \dots, c_{nn}) \in D \setminus \{\pi_\ell \cup \pi_k\}$ for some $\ell \neq k$ and*

$$(1.7) \quad c_{ij} = \frac{\varepsilon_j \gamma_i \gamma_j}{n-1} \sqrt{\varepsilon_i \varepsilon_j \beta_i \beta_j}(c) \quad \forall i \neq j$$

where $\gamma_j = \pm 1$ for $1 \leq j \leq n$. Moreover, for any such fixed tensor T , the solutions are given by

$$(1.8) \quad \varphi(x) = k \exp \left(\frac{\delta}{\sqrt{(n-2)(n-1)}} \left(\sum_j \gamma_j \sqrt{\varepsilon_j \beta_j}(c) x_j \right) \right)$$

where k is a nonzero constant and $\delta = \pm 1$.

In Theorem 1.1, for each $c \in D \setminus \{\pi_\ell \cup \pi_k\}$, the expressions (1.7) define at least two and generically 2^{n-1} tensors T .

Theorem 1.2. *Let (R^n, g) be a pseudo-Euclidean space and let T be a non diagonal symmetric tensor as in (1.1) such that $\sum_i c_{ii} = 0$. Then there is a metric $\bar{g} = g/\varphi^2$ such that $\text{Ric } \bar{g} = T$, if and only if, $c = (c_{11}, \dots, c_{nn}) \in (D \cup L) \setminus \{\pi_\ell \cup \pi_k\}$ for some $\ell \neq k$ and*

$$(1.9) \quad c_{ij} = \begin{cases} \varepsilon_j \gamma_i \gamma_j \sqrt{\varepsilon_i \varepsilon_j c_{ii} c_{jj}} & \forall i \neq j \quad \text{if } c \in D \setminus \{\pi_\ell \cup \pi_k\} \\ -\varepsilon_j \gamma_i \gamma_j \sqrt{\varepsilon_i \varepsilon_j c_{ii} c_{jj}} & \forall i \neq j \quad \text{if } c \in L \setminus \{\pi_\ell \cup \pi_k\} \end{cases}$$

where $\gamma_j = \pm 1$ for $1 \leq j \leq n$. Moreover, for any such fixed tensor T , the function φ is constant if g is the Euclidean metric and otherwise it is given by

$$(1.10) \quad \varphi(x) = \begin{cases} k_1 \exp \left(\sum_j h_j(x_j) \right) + k_2 \exp \left(-\sum_j h_j(x_j) \right), & \text{if } c \in D \setminus \{\pi_\ell \cup \pi_k\} \\ k_1 \cos \left(\sum_j h_j(x_j) \right) + k_2 \sin \left(\sum_j h_j(x_j) \right), & \text{if } c \in L \setminus \{\pi_\ell \cup \pi_k\} \end{cases}$$

and

$$(1.11) \quad h_j(x_j) = \begin{cases} \sqrt{\frac{\varepsilon_j c_{jj}}{n-2}} \gamma_j x_j. & \text{if } c \in D \setminus \{\pi_\ell \cup \pi_k\} \\ \sqrt{\frac{-\varepsilon_j c_{jj}}{n-2}} \gamma_j x_j. & \text{if } c \in L \setminus \{\pi_\ell \cup \pi_k\} \end{cases}$$

Theorem 1.3. *Let (R^n, g) be a pseudo-Euclidean space and let $T = \sum_{i=1}^n \varepsilon_i c_{ii} dx_i^2$ be a non zero diagonal tensor. Then there exists $\bar{g} = g/\varphi^2$ such that $\text{Ric } \bar{g} = T$, if and only if, $T = T_k$ for some k , $1 \leq k \leq n$ where $T_k = b \sum_{i \neq k} \varepsilon_i dx_i^2$ with $b \varepsilon_k < 0$. In this case,*

$$\bar{g}_{ij} = \delta_{ij} \varepsilon_i \exp \left(a - 2\delta \sqrt{\frac{-b \varepsilon_k}{n-2}} x_k \right)$$

where $\delta = \pm 1$ and $a \in R$.

The tensors T_k considered in this theorem are singular. However, in contrast with the results of [D2], they admit metrics \bar{g} , globally defined on R^n such that $\text{Ric } \bar{g} = T_k$.

Theorem 1.4. *Let (R^n, g) be a pseudo-Euclidean space. Then there exists $\bar{g} = g/\varphi^2$ such that $\text{Ric } \bar{g} = 0$, if and only if,*

$$(1.12) \quad \varphi = \sum_{j=1}^n (A\varepsilon_j x_j^2 + B_j x_j + C_j), \quad \text{where} \quad 4A \sum_j C_j - \sum_j \varepsilon_j B_j^2 = 0$$

and the constants $A, C_j, B_j \in R$.

As a consequence of the above theorems we obtain:

Corollary 1.5. *Let (R^n, g) be a pseudo-Euclidean space. For each $\lambda \in R$ ($\lambda \leq 0$ if g is the Euclidean metric), the equation*

$$(1.13) \quad -\varphi \Delta_g \varphi + \frac{n}{2} \|\nabla_g \varphi\|^2 + \lambda \varphi^2 = 0$$

has infinitely many solutions, of C^∞ class, globally defined on R^n .

- a): If $\lambda \neq 0$, then the functions given by (1.8) satisfy (1.13), whenever $c = (c_{11}, \dots, c_{nn}) \in D \setminus \{\pi_\ell \cup \pi_k\}$ is chosen such that $\lambda = \sum_{i=1}^n c_{ii}/2(n-1)$.
- b): If $\lambda = 0$, the functions given by (1.12) and by (1.10) where $c \in (D \cup L) \setminus \{\pi_\ell \cup \pi_k\}$ is chosen such that $\sum_{i=1}^n c_{ii} = 0$, are solutions of (1.13). In particular, the solutions given by (1.10) satisfy $\|\nabla_g \varphi\| = \Delta_g \varphi = 0$.

Corollary 1.6. *Let (R^n, g) be a pseudo-Euclidean space. For each n -tuple $c = (c_{11}, \dots, c_{nn}) \in D \setminus \{\pi_i \cup \pi_j\}$, such that $\sum_i c_{ii} \neq 0$, let $\beta_j(c)$ be the constants defined by (1.3). Consider the function $\bar{K} : R^n \rightarrow R$ given by*

$$(1.14) \quad \bar{K}(x) = \sum_i c_{ii} \exp \left(\frac{2\delta}{\sqrt{(n-2)(n-1)}} \left(\sum_j \gamma_j \sqrt{\varepsilon_j \beta_j(c)} x_j \right) \right)$$

where $\delta = \pm 1$, $\gamma_j = \pm 1$ for $1 \leq j \leq n$. Then the metric $\bar{g} = g/\varphi^2$, where φ is given by (1.8), has scalar curvature \bar{K} . In particular, if (R^n, g) is the Euclidean space then $\bar{K} < 0$.

Corollary 1.7. *Let (R^n, g) be a pseudo-Euclidean space. The metrics $\bar{g} = g/\varphi^2$, where φ is given by (1.10) and (1.12) have flat scalar curvature \bar{K} . In particular, in the latter case the metrics have flat sectional curvature.*

Corollary 1.8. *Let (R^n, g) be a pseudo-Euclidean space. For any constant symmetric tensor T , there are no complete metrics \bar{g} , conformal and nonhomothetic to g , such that $\text{Ric } \bar{g} = T$.*

We conclude this section by observing that the metrics \bar{g} , obtained in Theorems 1.1-1.3 satisfy the relation

$$\text{Ric } \bar{g} - \text{Ric } g = C.g \quad \text{where} \quad C = (c_{ij}) \quad \text{with} \quad c_{ij} = \frac{\varepsilon_j}{\varepsilon_i} c_{ji} \in R.$$

In [KR], Khünel and Rademacher, studied conformal metrics $\bar{g} = g/\varphi^2$ in semi-Riemannian manifolds (M, g) satisfying the relation $\text{Ric } \bar{g} - \text{Ric } g = (n-1)\lambda g$ where $\lambda \in R$. They showed that if M is a pseudo-Euclidean space, then $\lambda = 0$ and φ is constant. Consequently g and \bar{g} are homothetic. Moreover, they showed

that if (M, g) is a semi-Riemannian complete manifold and $\bar{g} = g/\varphi^2$ is globally defined, then M is necessarily a Riemannian manifold. Theorems 1.1, 1.2 and 1.3 show that this result does not hold for matrices C which are not multiple of the identity matrix.

2. PROOF OF THE MAIN RESULTS

We will start with some lemmas which will be used in the proof of Theorems 1.1-1.4.

Lemma 2.1. *Solving problem (1.2) is equivalent to studying the following system of equations*

$$(2.1) \quad \begin{cases} \varphi_{x_i x_i} = \varepsilon_i \left(\lambda_i \varphi + \frac{\|\nabla_g \varphi\|^2}{2\varphi} \right) \\ \varphi_{x_i x_j} = \frac{\varepsilon_j c_{ij}}{n-2} \varphi \end{cases} \quad 1 \leq i \neq j \leq n.$$

where

$$(2.2) \quad \lambda_i = \frac{2(n-1)c_{ii} - \sum_{\ell} c_{\ell\ell}}{2(n-1)(n-2)}$$

Proof. We know (see for example [E],[KR]), that if (M, g) is a semi-Riemannian manifold and $\bar{g} = g/\varphi^2$, then the Ricci tensors satisfy the relation

$$(2.3) \quad \text{Ric } \bar{g} - \text{Ric } g = \frac{1}{\varphi^2} \{ (n-2)\varphi \text{Hess}_g(\varphi) + (\varphi \Delta_g \varphi - (n-1)\|\nabla_g \varphi\|^2)g \}.$$

Since, $\text{Ric } g = 0$, using (2.3) we obtain that (1.2) is equivalent to studying the following system of equations

$$(2.4) \quad \frac{1}{\varphi^2} \{ (n-2)\varphi \text{Hess}_g(\varphi)_{ij} + (\varphi \Delta_g \varphi - (n-1)\|\nabla_g \varphi\|^2) g_{ij} \} = \varepsilon_j c_{ij}$$

where, for each $1 \leq i, j \leq n$

$$(\text{Hess}_g \varphi)_{ij} = \varphi_{x_i x_j}, \quad \Delta_g \varphi = \sum_i \varepsilon_i \varphi_{x_i x_i}, \quad \|\nabla_g \varphi\|^2 = \sum_i \varepsilon_i (\varphi_{x_i})^2.$$

The system of equations (2.4) is given by

$$(2.5) \quad \begin{cases} \frac{1}{\varphi^2} \{ (n-2)\varphi \varphi_{x_i x_i} + (\varphi \Delta_g \varphi - (n-1)\|\nabla_g \varphi\|^2) \varepsilon_i \} = \varepsilon_i c_{ii}, \\ \varphi_{x_i x_j} = \frac{\varepsilon_j c_{ij} \varphi}{n-2} \quad 1 \leq i \neq j \leq n. \end{cases}$$

Substituting $\Delta_g \varphi$ in the first n equations of (2.5) we have

$$(2.6) \quad \sum_{j \neq i} \varepsilon_j \varphi_{x_j x_j} + \varepsilon_i (n-1) \varphi_{x_i x_i} = c_{ii} \varphi + \frac{(n-1)\|\nabla_g \varphi\|^2}{\varphi} \quad \forall i, 1 \leq i \leq n.$$

For a fixed i , multiplying equation (2.6) by $(2n-3)$ and adding with the $(n-1)$ remaining equations we obtain

$$\varphi_{x_i x_i} = \varepsilon_i \left(\lambda_i \varphi + \frac{\|\nabla_g \varphi\|^2}{2\varphi} \right),$$

where λ_i is given by (2.2). The proof of the Lemma follows from (2.5) and (2.6). \square

Remark 2.2. For future use, considering $c = (c_{11}, \dots, c_{nn})$, we point out the following relations

$$(2.7) \quad (n-2)\lambda_i - \sum_k \lambda_k = \frac{\beta_i}{n-1}, \quad \forall 1 \leq i \leq n$$

$$(2.8) \quad \sum_i \frac{\beta_i}{n-1} = -2 \sum_i \lambda_i = -\sum_i \frac{c_{ii}}{n-1},$$

which follow from a straightforward computation by using (1.3) and (2.2).

Lemma 2.3. *If $\varphi : R^n \rightarrow R$ is a solution of the system of equations (2.1) then the first derivatives of φ are related by*

$$(2.9) \quad c_{ji}\varphi_{x_i} = \frac{\beta_i}{n-1}\varphi_{x_j} \quad \forall i \neq j$$

Proof. Since φ satisfies the system (2.1), it follows from the comutativity of the third order derivatives, that the following equations hold

$$(2.10) \quad (\lambda_i + \lambda_j)\varphi_{x_j} + \sum_{\substack{\ell \neq j \\ \ell \neq i}} \frac{c_{j\ell}}{n-2}\varphi_{x_\ell} = 0 \quad 1 \leq i \neq j \leq n.$$

If $n = 3$, then equation (2.10) is given by

$$(\lambda_i + \lambda_j)\varphi_{x_j} + c_{j\ell}\varphi_{x_\ell} = 0 \quad 1 \leq i \neq j \neq \ell \leq 3$$

which reduces to (2.9) as a consequence of (2.7). If $n \geq 4$, for a fixed pair (i, j) , multiplying equation (2.10) by $-(n-3)$ and adding with the $n-2$ equations (2.10) given by the pairs (k, j) , with $k \neq i$ and $k \neq j$ we obtain equation

$$c_{ji}\varphi_{x_i} = \left((n-2)\lambda_i - \sum_k \lambda_k \right) \varphi_{x_j} \quad \forall i \neq j.$$

Equation (2.9) follows from (2.7). \square

Our next Lemma shows that the symmetric tensors T given by (1.1), for which the system of equations (1.2) has a solution, are necessarily determined by its diagonal elements.

Lemma 2.4. *Let (R^n, g) be a pseudo-Euclidean space and let $T = \sum_{i,j} \varepsilon_j c_{ij} dx_i \otimes$*

dx_j be a non-diagonal symmetric constant tensor. If there exists a metric $\bar{g} = g/\varphi^2$ such that $\text{Ric } \bar{g} = T$, then

$$(2.11) \quad \frac{\|\nabla_g \varphi\|^2}{2\varphi} = -\sum_{k=1}^n \frac{\lambda_k \varphi}{n-2}$$

and the components of the tensor T are such that $c = (c_{11}, \dots, c_{nn}) \in (D \cup L) \setminus \{\pi_r \cup \pi_\ell\}$ for some pair (r, ℓ) , $1 \leq r \neq \ell \leq n$, D , L and π_r are given by (1.4) (5) and (1.6) and

$$(2.12) \quad c_{ij} = \pm \frac{\sqrt{\varepsilon_i \varepsilon_j \beta_i \beta_j}}{n-1} (c_{11}, \dots, c_{nn}) \quad i \neq j$$

where $\beta_i(c_{11}, \dots, c_{nn})$ is given by (1.3) and λ_i by (2.2).

Proof. Taking the derivative of (2.9) with respect to the variable x_j and using the system (2.1) we obtain

$$(2.13) \quad \frac{\beta_i}{n-1} \left(\varepsilon_j \left(\lambda_j \varphi + \frac{\|\nabla_g \varphi\|^2}{2\varphi} \right) \right) = \frac{c_{ji}^2}{n-2} \varepsilon_i \varphi$$

Now taking the derivative of (2.9) with respect to the variable x_i we have

$$(2.14) \quad c_{ji} \left(\lambda_i \varphi + \frac{\|\nabla_g \varphi\|^2}{2\varphi} \right) = \frac{\beta_i}{(n-1)(n-2)} c_{ji} \varphi$$

Since, there exists at least one term $c_{ji} \neq 0$ for $j \neq i$, we obtain equation (2.11) directly from (2.14) and (2.7). Now, substituing (2.11) in (2.13) and using again (2.7) for all j , we obtain (2.12). In order to have the non-diagonal terms well defined, we need to have $\varepsilon_i \varepsilon_j \beta_i \beta_j \geq 0$ for all $i \neq j$. Moreover, since T is a non-diagonal tensor, we conclude that $\beta_r^2 + \beta_\ell^2 \neq 0$, for some $r \neq \ell$. Therefore, (c_{11}, \dots, c_{nn}) belongs to $D \cup L \setminus \{\pi_r \cup \pi_\ell\}$. \square

Remark 2.5. Let (R^n, g) $n \geq 3$, be a pseudo-Euclidean space, i.e. $g_{ij} = \delta_{ij} \varepsilon_i$, $\varepsilon_i = \pm 1$. For any fixed pair $k \neq s$, $D \setminus \{\pi_k \cup \pi_s\}$ (resp. $L \setminus \{\pi_k \cup \pi_s\}$) is a non-empty subset of R^n . In fact, let $a_j \in R$ be such that $a_j \leq 0$ (resp. $a_j \geq 0$ for $1 \leq j \leq n$ and $a_k a_s \neq 0$). We consider $x_\ell = \sum_{j \neq \ell} a_j \varepsilon_j$. Then we have $\beta_j = -(n-1)a_j \varepsilon_j$ and hence (x_1, \dots, x_n) belongs to $D \setminus \{\pi_k \cup \pi_s\}$. (resp. $L \setminus \{\pi_k \cup \pi_s\}$).

We consider the map $S : R^n \rightarrow R$ such that for each $x = (x_1, \dots, x_n) \in R^n$ associates $S(x) = \sum_i x_i$. Let (R^n, g) be a pseudo-Euclidean space. For any fixed pair $k \neq s$, let S_1 (resp. S_2) be the restriction of the function S to $D \setminus \{\pi_k \cup \pi_s\}$ (resp. $L \setminus \{\pi_k \cup \pi_s\}$). Then, one can easily see that if g is the Euclidean metric then the image of S_1 (resp. S_2) is $(-\infty, 0)$ (resp. $(0, \infty)$). Otherwise, the image of S_1 and S_2 is the whole real line.

Proof of Theorem 1.1. From Lemma 2.1 solving the system (1.2) is equivalent to obtaining a nonvanishing solution φ of (2.1). It follows from Lemma 2.4 and (2.7), that if φ satisfies the system (2.1) then $c = (c_{11}, \dots, c_{nn}) \in (D \cup L) \setminus \{\pi_r \cup \pi_s\}$ for some $r \neq s$ and φ is a solution of

$$(2.15) \quad \begin{cases} \varphi_{x_i x_i} = \alpha_i \varphi \\ \varphi_{x_i x_j} = \frac{\varepsilon_j c_{ij}}{n-2} \varphi \end{cases}$$

where ,

$$(2.16) \quad \alpha_i = \frac{\varepsilon_i \beta_i(c)}{(n-1)(n-2)}, \quad c_{ij} = \pm \frac{1}{n-1} \sqrt{\varepsilon_i \varepsilon_j \beta_i \beta_j}(c)$$

and β_i is given by (1.3). Moreover, φ satisfies (2.11).

Assume that $(c_{11}, \dots, c_{nn}) \in L \setminus \{\pi_r \cup \pi_s\}$. Then $\alpha_s < 0$ and consequently the solutions of (2.15) are given by

$$(2.17) \quad \varphi(x_1, \dots, x_n) = f(\hat{x}_s) \cos(\sqrt{-\alpha_s} x_s) + g(\hat{x}_s) \sin(\sqrt{-\alpha_s} x_s)$$

where f and g are smooth functions of $\hat{x}_s = (x_1, \dots, x_{s-1}, x_{s+1}, \dots, x_n)$.

Since $\varphi_{x_s x_j} = \frac{\varepsilon_j c_{sj}}{n-2} \varphi$ for all $j \neq s$ we obtain that

$$(f)_{x_j} = \frac{-\varepsilon_j c_{sj}}{(n-2)\sqrt{-\alpha_s}} g \quad \text{and} \quad (g)_{x_j} = \frac{\varepsilon_j c_{sj}}{(n-2)\sqrt{-\alpha_s}} f$$

for all $j \neq s$. Therefore, we have

$$\|\nabla_g \varphi\|^2 = - \sum_{i=1}^n \frac{\beta_i}{(n-1)(n-2)} (f \sin(\sqrt{-\alpha_s} x_s) - g \cos(\sqrt{-\alpha_s} x_s))^2$$

On the other hand, from (2.11) we have

$$\|\nabla_g \varphi\|^2 = \frac{-2}{n-2} \sum_i \lambda_i (f \cos(\sqrt{-\alpha_s} x_s) + g \sin(\sqrt{-\alpha_s} x_s))^2.$$

Comparing those relations we get, as a consequence of (2.8), that

$$(f^2(\hat{x}) + g^2(\hat{x})) \sum_{i=1}^n c_{ii} = 0.$$

Since $\sum_{i=1}^n c_{ii} \neq 0$, we conclude that if $c = (c_{11}, \dots, c_{nn}) \in L \setminus \{\pi_s \cup \pi_r\}$, then the system (2.15) does not admit non-zero solution.

If $c \in D \setminus \{\pi_s \cup \pi_r\}$, then $\alpha_j \geq 0$ for all j . Let

$$\mathfrak{S} = \{j, 1 \leq j \leq n, \alpha_j > 0\}.$$

It follows from the first equation of (2.15) that

$$(2.18) \quad \varphi(x) = \tilde{f} \exp\left(\sum_{j \in \mathfrak{S}} \gamma_j \sqrt{\alpha_j} x_j\right) + \tilde{g} \exp\left(-\sum_{j \in \mathfrak{S}} \gamma_j \sqrt{\alpha_j} x_j\right)$$

where $\gamma_j = \pm 1$, \tilde{f} and \tilde{g} are functions of the variables x_i with $i \notin \mathfrak{S}$. From the second equation of (2.15), we have that

$$\varphi_{x_i x_j} = 0 \quad \text{for all } j \in \mathfrak{S} \text{ and } i \notin \mathfrak{S}.$$

Therefore, we conclude that the functions \tilde{f} and \tilde{g} are constant.

If $i, j \in \mathfrak{S}$, it follows from (2.18), (2.16) and the second equation of (2.15) that

$$c_{ij} = \frac{\varepsilon_j \gamma_i \gamma_j}{n-1} \sqrt{\varepsilon_i \varepsilon_j \beta_i \beta_j}.$$

Finally, using the relation (2.11) one concludes that $\tilde{f} = 0$ or $\tilde{g} = 0$.

Conversely, for each $c = (c_{11}, \dots, c_{nn}) \in D \setminus \{\pi_\ell \cup \pi_k\}$, such that $\sum_i c_{ii} \neq 0$, let c_{ij} for $i \neq j$ be defined by (1.7), where we have chosen $\gamma_j = \pm 1$ for $1 \leq j \leq n$. The tensor T is fixed with any such choice. Then the two functions φ defined by (1.8) satisfy (2.1) and therefore provide metrics $\bar{g} = g/\varphi^2$ for which $\text{Ric } \bar{g} = T$. \square

Proof of Theorem 1.2. By hypothesis T is a nondiagonal tensor such that $\sum_i c_{ii} = 0$. Therefore, it follows from Lemma 2.4, (2.8), (1.3), (2.2), (2.11) and (2.12) that the system of equations (2.1) is given by

$$(2.19) \quad \varphi_{x_i x_i} = \frac{\varepsilon_i c_{ii}}{n-2} \varphi$$

$$(2.20) \quad \varphi_{x_i x_j} = \frac{\varepsilon_j c_{ij}}{n-2} \varphi$$

where $c = (c_{11}, \dots, c_{nn}) \in (L \cup D) \setminus (\pi_\ell \cup \pi_k)$

$$c_{ij} = \pm \sqrt{\varepsilon_i \varepsilon_j c_{ii} c_{jj}},$$

$$\begin{aligned} D &= \{(x_1, \dots, x_n) \in R^n; \varepsilon_j x_j \geq 0 \forall j\}, \\ L &= \{(x_1, \dots, x_n) \in R^n; \varepsilon_j x_j \leq 0 \forall j\}, \\ \pi_j &= \{(x_1, \dots, x_n) \in R^n; x_j = 0\}. \end{aligned}$$

Moreover, $\|\nabla_g \varphi\|^2 = 0$. Therefore, if g is the Euclidean metric we conclude that φ is necessarily constant.

If $c = (c_{11}, \dots, c_{nn}) \in D \setminus (\pi_\ell \cup \pi_k)$, then $\varepsilon_i c_{ii} \geq 0$ for all i . Let \mathfrak{S} be the set of indices i such that $c_{ii} \neq 0$. Then it follows from (2.19) that

$$\varphi(x) = k_1 \exp\left(\sum_{j \in \mathfrak{S}} h_j(x_j)\right) + k_2 \exp\left(-\sum_{j \in \mathfrak{S}} h_j(x_j)\right)$$

where h_j is defined by (1.11) and k_1, k_2 are functions which depend on x_i for $i \notin \mathfrak{S}$. From equation (2.20) we conclude that k_1 and k_2 are constants and

$$c_{ij} = \varepsilon_j \gamma_i \gamma_j \sqrt{\varepsilon_i \varepsilon_j c_{ii} c_{jj}}.$$

If $c \in L \setminus (\pi_\ell \cup \pi_k)$, then $\varepsilon_i c_{ii} \leq 0$ for all i . Let \mathfrak{S} be the set of indices i such that $c_{ii} \neq 0$. Then it follows from (2.19) that

$$\varphi(x) = k_1 \cos\left(\sum_{j \in \mathfrak{S}} h_j(x_j)\right) + k_2 \sin\left(-\sum_{j \in \mathfrak{S}} h_j(x_j)\right)$$

where k_1 and k_2 are functions which depend on x_i for $i \notin \mathfrak{S}$. From equation (2.20) we conclude that k_1 and k_2 are constants and

$$c_{ij} = -\varepsilon_j \gamma_i \gamma_j \sqrt{\varepsilon_i \varepsilon_j c_{ii} c_{jj}}.$$

The converse of this theorem is a straightforward computation. \square

Proof of Theorem 1.3. Since $T = \sum_i \varepsilon_i c_{ii} dx_i^2$ is a nonzero tensor, it follows from Lemma 2.3, that if φ satisfies the system of equations (2.1), then φ is not constant and

$$0 = \beta_i(c) \varphi_{x_j} \quad \forall i \neq j.$$

Let k be such that $\varphi_{x_k} \neq 0$. Since $n \geq 3$, there exists $i_1 \neq i_2$ distinct from k such that $\beta_{i_1} = \beta_{i_2} = 0$. It follows from (1.3) that $c_{i_1 i_1} = c_{i_2 i_2}$. Hence, for all $i \neq k$, $c_{ii} = b$ and therefore $\sum_j c_{jj} = (n-1)b + c_{kk}$. Since for all $i \neq k$ we have $\beta_i = 0$, we conclude from (1.3) that $c_{kk} = 0$. It follows that φ does not depend on more than one variable. In fact, otherwise $c_{ii} = 0$ for all i which is a contradiction since T is a nonzero tensor.

So we have that $\varphi = \varphi(x_k)$ for some $k; 1 \leq k \leq n$. Moreover, $c_{ii} = b \neq 0$ for all $i \neq k$ and $c_{kk} = 0$, i.e. $T = T_k$. In this case, the system (2.1) is given by

$$(2.21) \quad \begin{cases} \frac{\varepsilon_k (\varphi'(x_k))^2}{\varphi} + \frac{b\varphi}{n-2} = 0 \\ 2\varepsilon_k \varphi''(x_k) + \frac{b\varphi}{n-2} - \frac{\varepsilon_k (\varphi'(x_k))^2}{\varphi} = 0. \end{cases}$$

It follows from the first equation of (2.21) that $b\varepsilon_k < 0$ and

$$(2.22) \quad \varphi(x_k) = \frac{1}{A} \exp\left(\delta \sqrt{\frac{-b\varepsilon_k}{n-2}} x_k\right)$$

where $A \neq 0$ is a real constant and $\delta = \pm 1$. The second equation of (2.21) is satisfied by φ . Therefore, $\bar{g}_{ij} = \delta_{ij} \varepsilon_i \exp\left(a - 2\delta \sqrt{\frac{-\varepsilon_k b}{n-2}} x_k\right)$ satisfies $\text{Ric } \bar{g} = T_k$.

Conversely, for $T = T_k$ the functions φ defined by (2.22) define metrics \bar{g} for which $\text{Ric } \bar{g} = T_k$. \square

Proof of Theorem 1.4. When $T \equiv 0$, it follows from Lemma 2.1 that φ satisfies the system of equations (2.1), where $\lambda_i = 0$ for all i . Therefore, it is easy to see that φ is given by (1.12). \square

Proof of Corollary 1.5. From Theorems 1.1, 1.2 and 1.4, we have that the functions φ , given by (1.8), (1.10) and (1.12) are solutions of the system (2.1). In particular, from (2.4) φ also satisfies the equations

$$\frac{1}{\varphi^2} \left\{ \varepsilon_i (n-2) \varphi \varphi_{x_i x_i} + \varphi \Delta_g \varphi - (n-1) \|\nabla_g \varphi\|^2 \right\} = c_{ii}$$

where for all $1 \leq i \leq n$.

Equation (1.13) is obtained by adding these equations on i . If $\lambda \neq 0$, there are infinitely many ways to obtain $\lambda = \sum_{i=1}^n c_{ii}/2(n-1)$ with $c = (c_{11}, \dots, c_{nn}) \in D \setminus \{\pi_k \cup \pi_s\}$. We conclude that equation (1.13) has infinitely many solutions given by (1.8). If (R^n, g) is the Euclidean space, it is easy to see that, if $c \in D$ then $c_{ii} \leq 0$ for all i , hence $\lambda \in (-\infty, 0]$.

Similarly, when $\lambda = 0$, there are infinitely many n -tuples $c \in (D \cup L) \setminus (\pi_\ell \cup \pi_k)$ such that $\sum_i c_{ii} = 0$. Hence, the functions φ given by (1.10) are solutions of (1.13). Moreover, the family of functions φ given by (1.12) are also solutions of (1.13) when $\lambda = 0$. \square

Proof of Corollary 1.6. It follows from the relation (2.3) that, if (R^n, g) with $n \geq 3$ is the pseudo-Euclidean space and $\bar{K} : R^n \rightarrow R$ is a smooth function, to find $\bar{g} = g/\varphi^2$ with scalar curvature \bar{K} is equivalent to solving the following differential equation

$$(2.23) \quad -\varphi \Delta_g \varphi + \frac{n}{2} \|\nabla_g \varphi\|^2 + \frac{\bar{K}}{2(n-1)} = 0.$$

Since $\bar{K} = \sum_{ij} \bar{g}^{ij} \bar{R}_{ij}$, if

$$\bar{K} = \lambda \exp\left(\frac{2\delta}{\sqrt{(n-2)(n-1)}} \left(\sum_j \gamma_j \sqrt{\varepsilon_j \beta_j} x_j\right)\right),$$

where β_j is given by (1.3), it follows from Corollary 1.4 that the functions given in (1.8) are solutions of the equation (36), showing that there exist metrics $\bar{g} = g/\varphi^2$ with scalar curvature \bar{K} . If (R^n, g) is the Euclidean space we have that $\sum c_{ii} < 0$ and consequently $\bar{K} < 0$. \square

Proof of Corollary 1.7. It is a straightforward computation which follows from Theorems 1.2 and 1.4. \square

Proof of Corollary 1.8. For each fixed tensor T as in Theorems 1.1 and 1.3, there exist two semi-Riemannian metrics (given by $\delta = \pm 1$) in the same conformal class which have pointwise the same Ricci tensor. Since they are not homothetic to each other, it follows from the results of [F] and [KR, Corollary 2] that they are not complete. A similar argument applies to the metrics obtained in Theorem 1.2 when $c \in D \setminus \{\pi_\ell \cup \pi_k\}$. In the remaining cases, the metric $\bar{g} = g/\varphi^2$ has singularity points. \square

We conclude observing partial results were obtained in [P]. A similar theory in the hyperbolic space $H^n(-1)$ will be treated in another paper. Moreover, the techniques introduced in this paper were also used to obtain our results in [PT], on the problem of finding metrics g , conformal to the pseudo-euclidean metric, satisfying the equation $\text{Ric } g - Kg/2 = T$, where K is the scalar curvature of g and T is a constant symmetric tensor.

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